

AIAA SciTech 2020

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National Aeronautics and  
Space Administration



# SBPW3: Propagation Workshop Results using sBOOM

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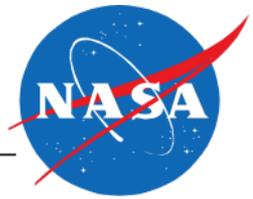


*A Starred Legacy, A Soaring Future*



# Outline

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- Summary of Cases Analyzed
- Boom Propagation Code Details
- Cases
  - Ground Signatures
  - Loudness metrics
- Highlights
- Summary

# Summary of Cases Analyzed

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- NASA trimmed low-boom concept - C25P
  - Required runs with measured atmospheric profiles
  - Lateral cut-off analysis
  - Optional focus boom simulations



# Summary of Cases Analyzed



- NASA trimmed low-boom concept - C25P
  - Required runs with measured atmospheric profiles
  - Lateral cut-off analysis
  - Optional focus boom simulations



- NASA-Lockheed Low-Boom Flight Demonstrator (LBFD): A variant of X-59 QueSST
  - Required runs with measured and standard atmospheres

# Propagation Prediction Code: sBOOM



## sBOOM

- Propagation based on lossy Quasi-1D Burgers equation

$$\frac{\partial p}{\partial \sigma} = \frac{\partial B}{\partial \sigma} p + \frac{\beta \Omega}{2 \rho_0 c_0^3} \left( \frac{c_0}{v_g} \right) \frac{\partial p^2}{\partial \tau} + \frac{\delta \Omega^2}{2 \rho_0 c_0^3} \left( \frac{c_0}{v_g} \right) \frac{\partial^2 p}{\partial \tau^2} + \sum_v \frac{m_v}{2 c_0} \frac{t_v \Omega^2}{1 + t_v \Omega \frac{\partial}{\partial \tau}} \left( \frac{c_0}{v_g} \right) \frac{\partial^2 p}{\partial \tau^2}$$

$$B = \sqrt{\frac{\rho c S_0 D_0^2}{\rho_0 c_0 S D^2} \left( \frac{c v_{g0}}{D_0} \right) \left( \frac{c_0 v_g}{D} \right)}, \quad v_g = |c \cdot \bar{n} + \bar{w}|, \quad D = 1 + \frac{\bar{w} \cdot \bar{n}}{c}, \quad \Omega = \frac{1}{D}$$

- Ray Path Equations:

$$\frac{dx}{dt} = \bar{w} + c^2 q D \quad \frac{dq}{dt} = - \left[ \frac{\nabla c}{c D} + \sum_{i=1}^3 q_i \nabla w_i \right] \quad q = \frac{\bar{n}}{c + \bar{w} \cdot \bar{n}}$$

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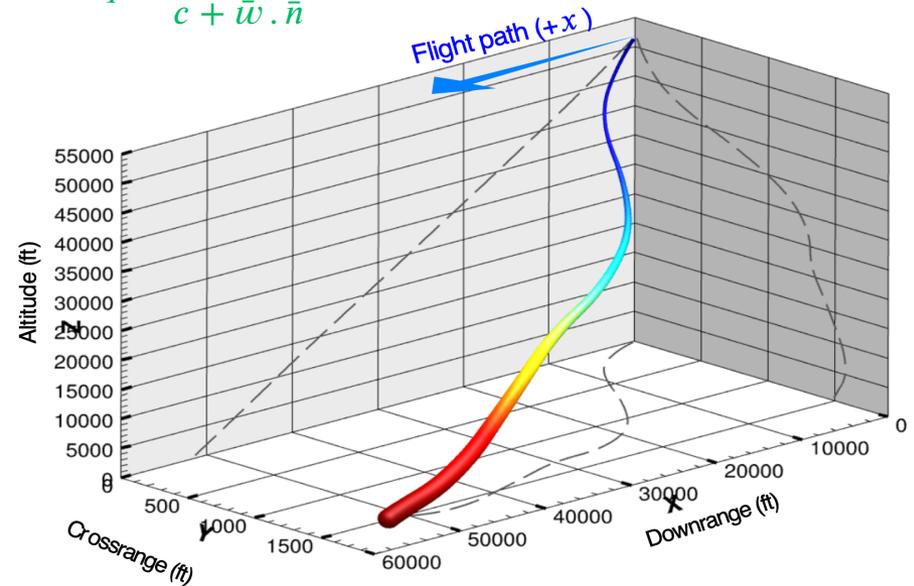
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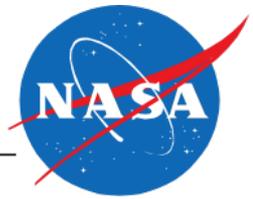
- **Features and capabilities**

- Under-track, off-track signatures with winds
- Acceleration, turn-rates, climb-rates, maneuvers and focus predictions by interfacing with Lossy Nonlinear Tricomi Equation (LNTE)
- Design friendly sensitivities and adjoint error estimates



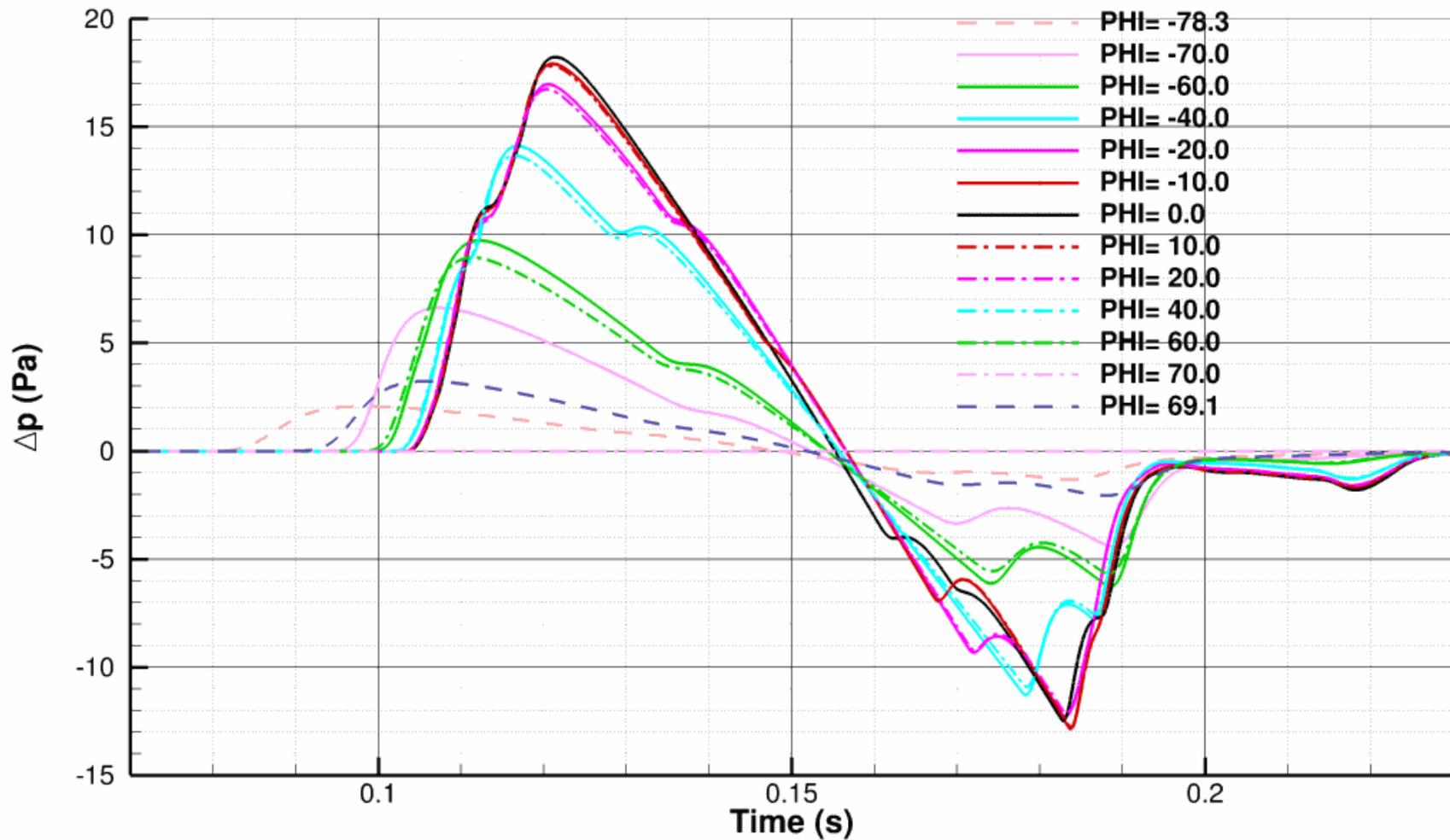
sBOOM is under active development. Contact [Sriram.Rallabhandi@nasa.gov](mailto:Sriram.Rallabhandi@nasa.gov) to get a copy of sBOOM

# Run Parameters

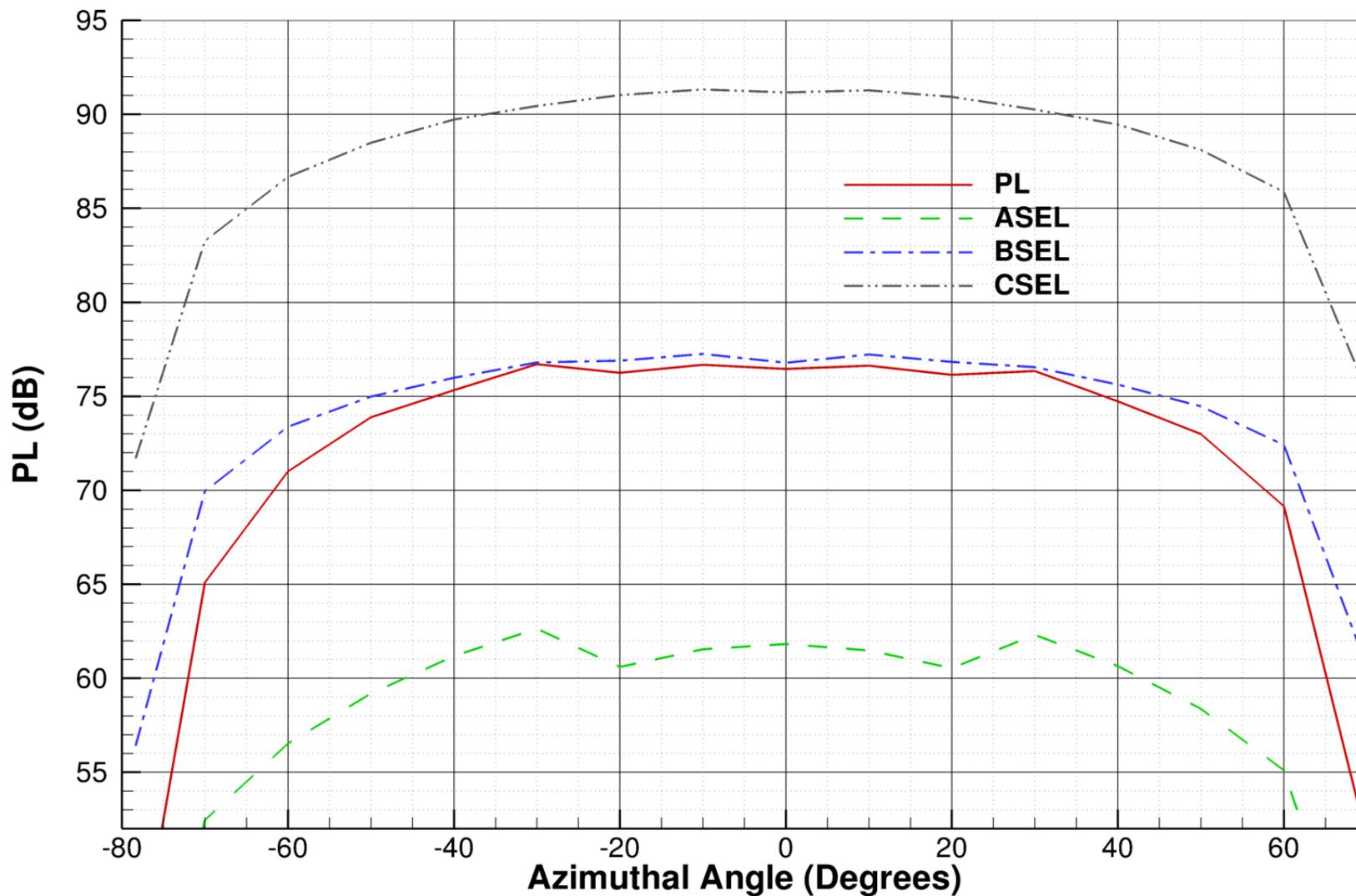


- All azimuthal angles run in parallel
- Computing platform:
  - OSX running macOS Mojave (10.14.6)
    - CPU: 2.5 GHz i7
    - RAM: 16GB, 1600 MHz DDR3
  - NASA Langley mid-range computing facility
    - Single node of SGI ICE Altix Cluster
- No pre-processing of near-field data
- Computational run times
  - Typical run times for edge-to-edge carpet predictions
    - ~30 seconds wall-time @ sampling frequency = 100 KHz (16 azimuths)
    - ~130 seconds wall-time @ sampling frequency = 200 KHz (16 azimuths)
- Sampling frequency determined by adjoint-error correction approach by continuously embedding uniformly refined grid
  - 100 KHz sufficient to resolve loudness BSEL to within 0.1 dB
  - 400 KHz sufficient to resolve loudness BSEL to within 0.02 dB

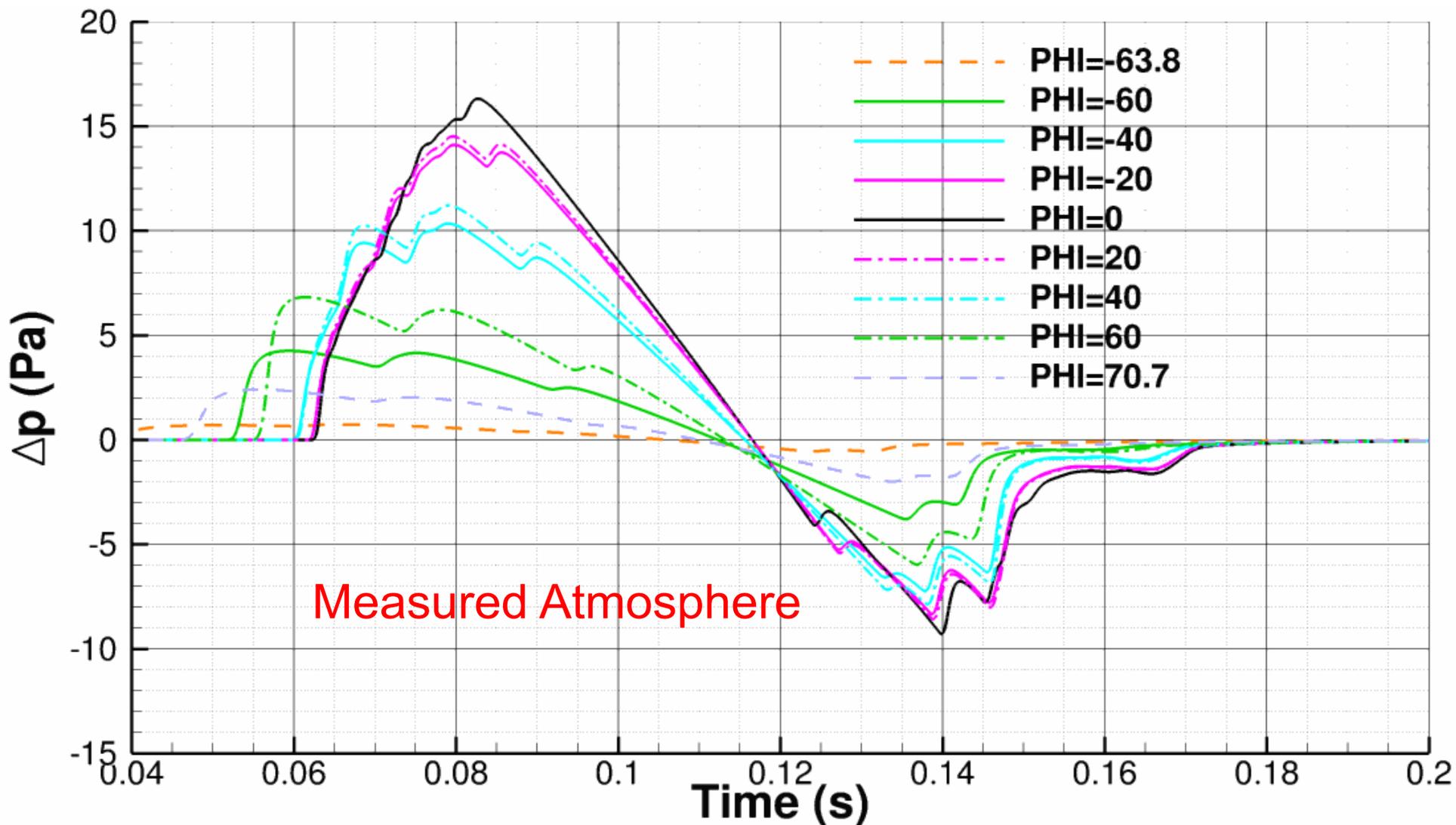
# Case1: Ground Signatures



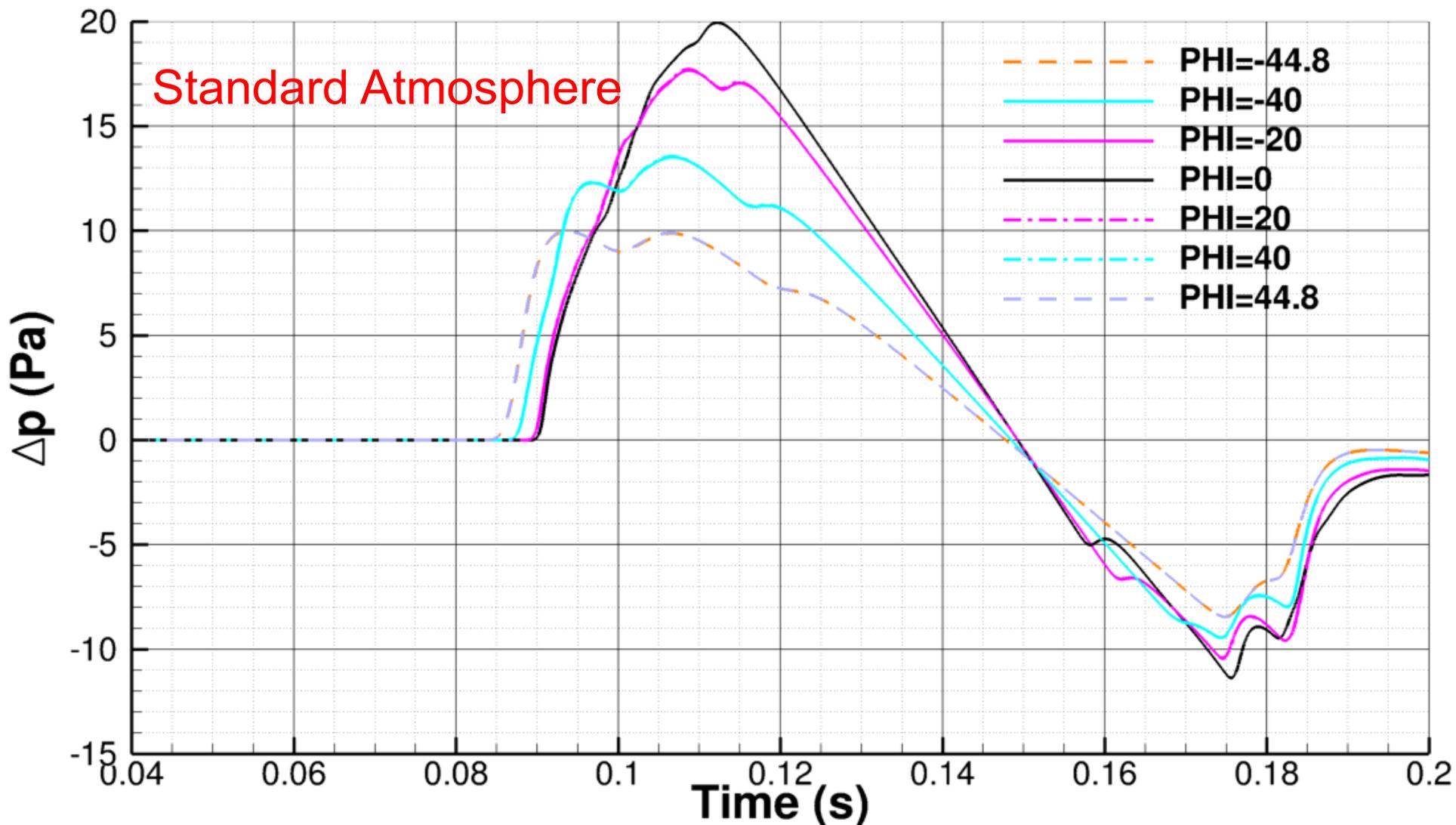
# Case1: Loudness Metrics



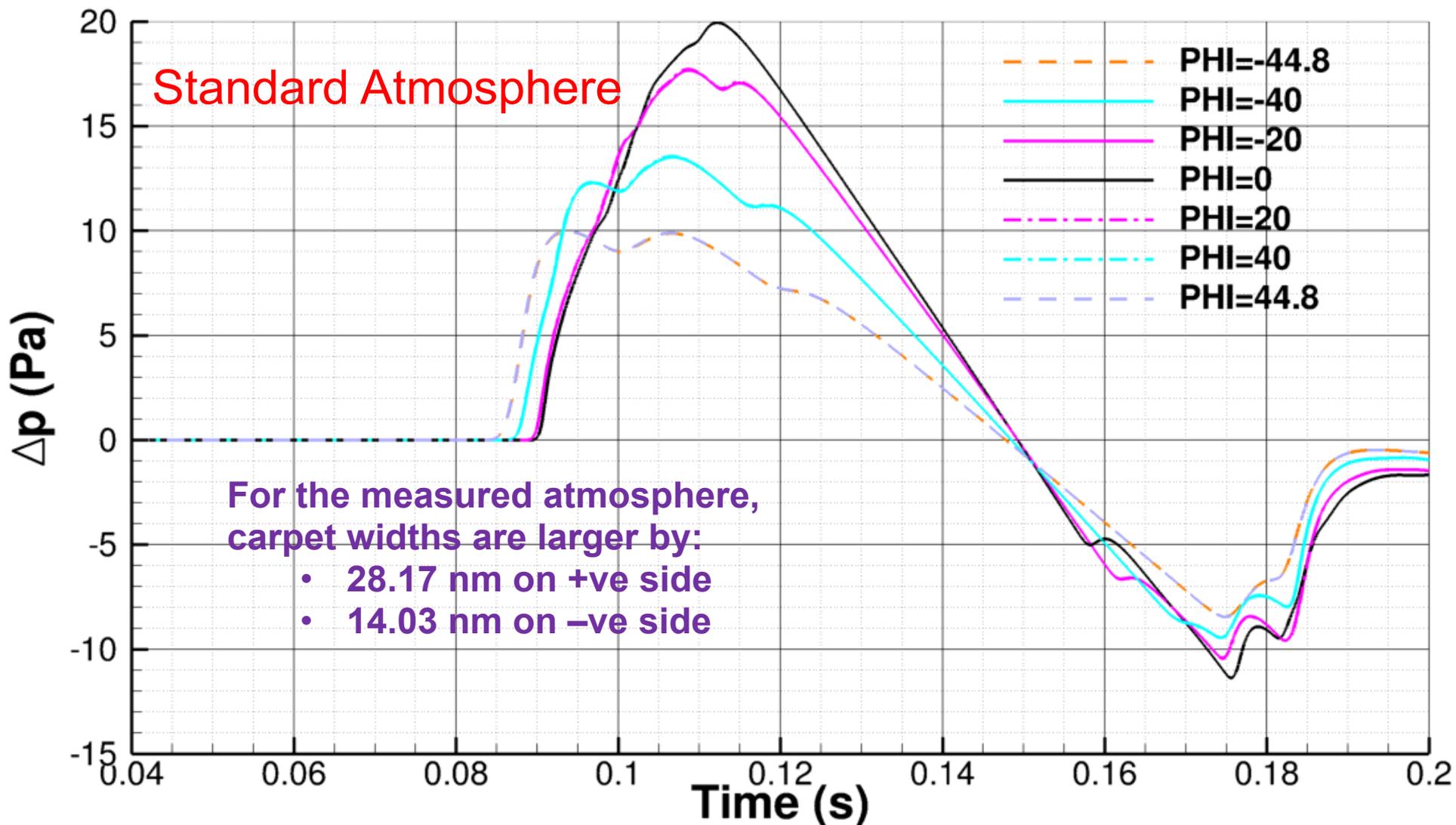
# Case2: Ground Signatures



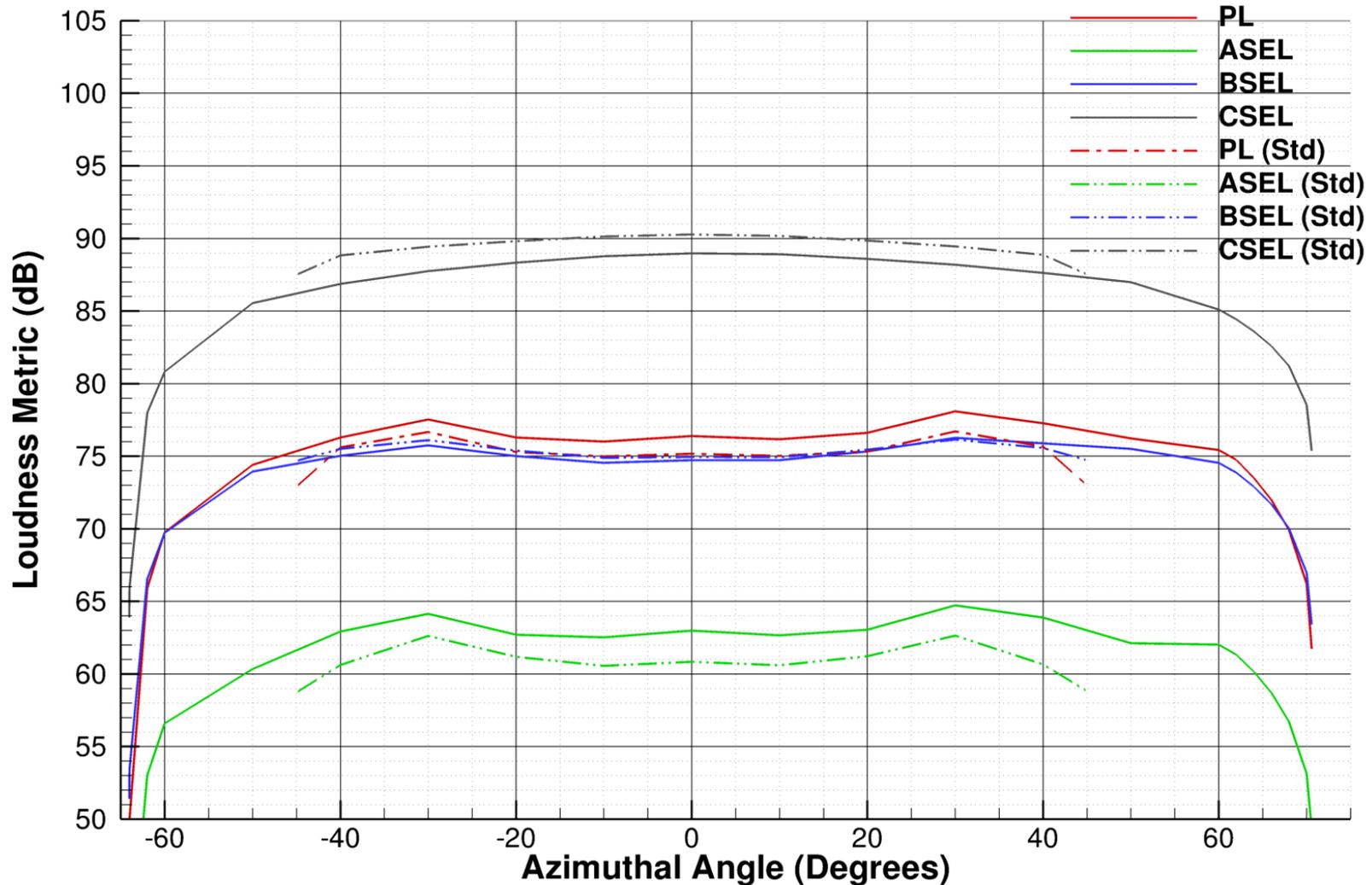
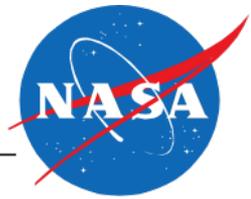
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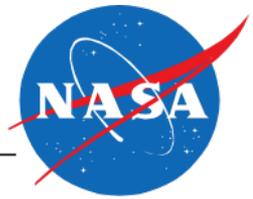
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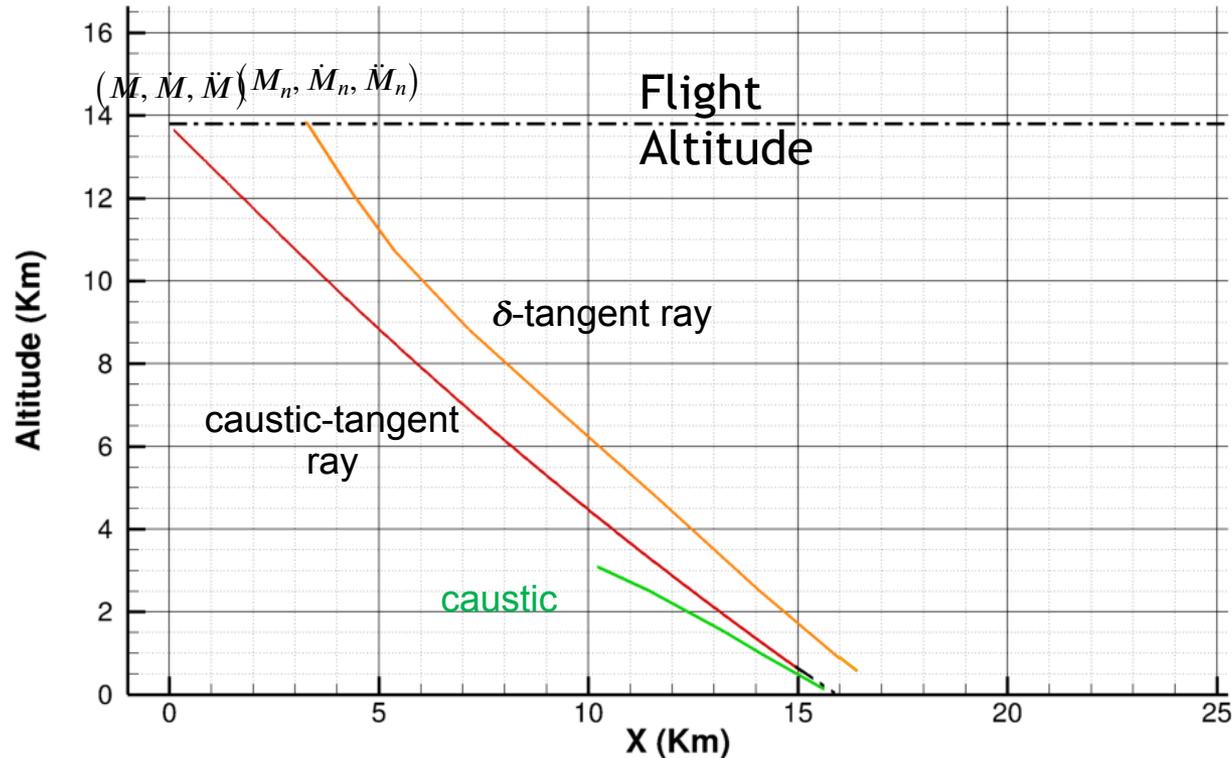
# Case2: Loudness Metrics



# Case1: Optional Focus Analysis



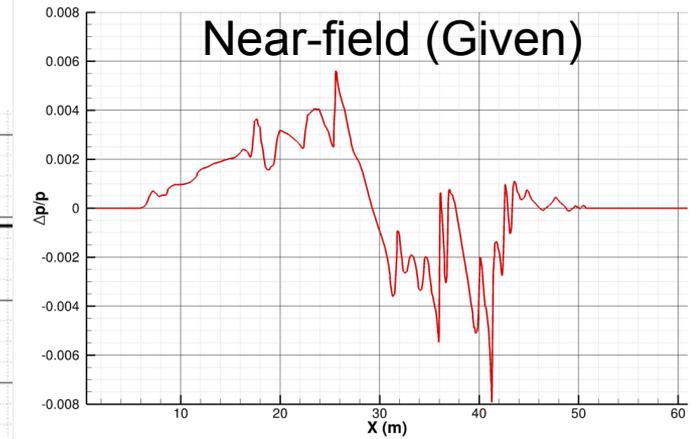
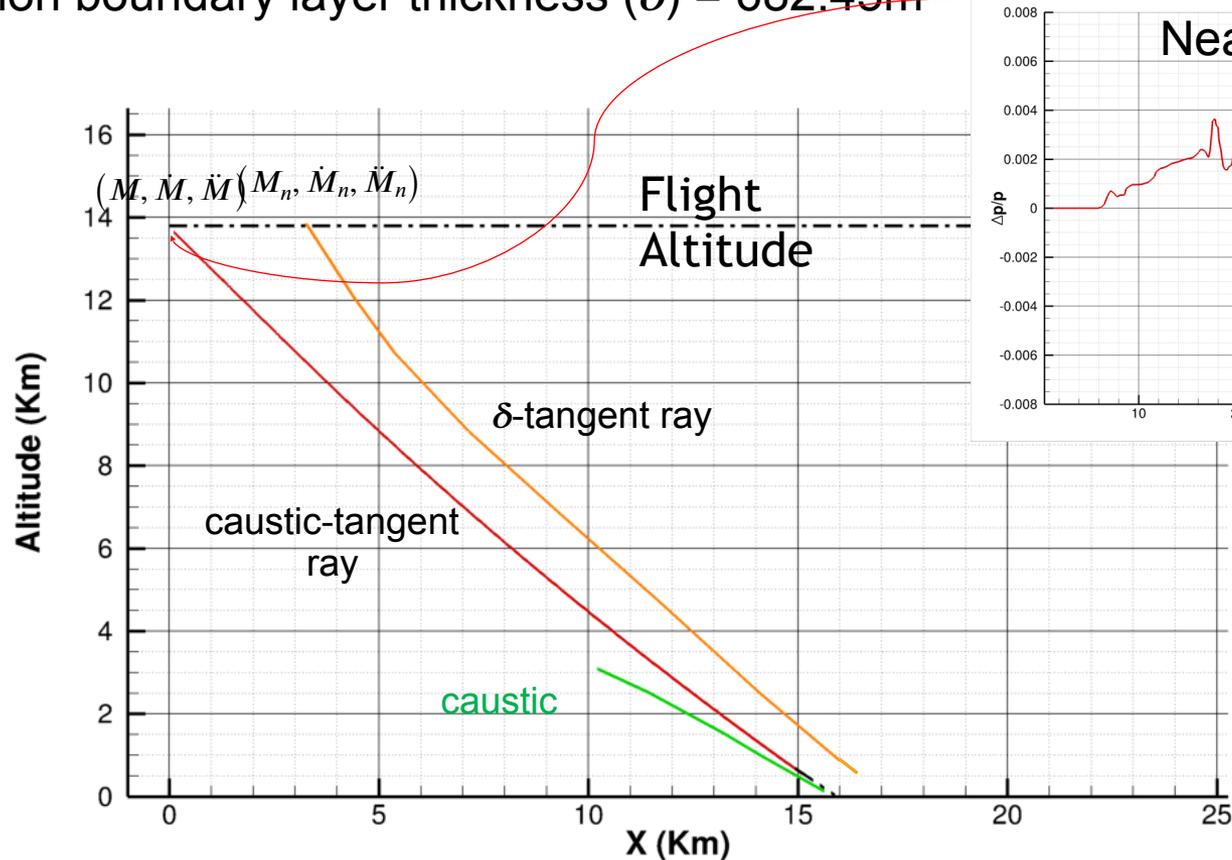
- $(M, \dot{M}, \ddot{M}) = (1.4121, 0.015681, 0.000359)$
- Diffraction boundary layer thickness  $(\delta) = 682.45\text{m}$



# Case1: Optional Focus Analysis



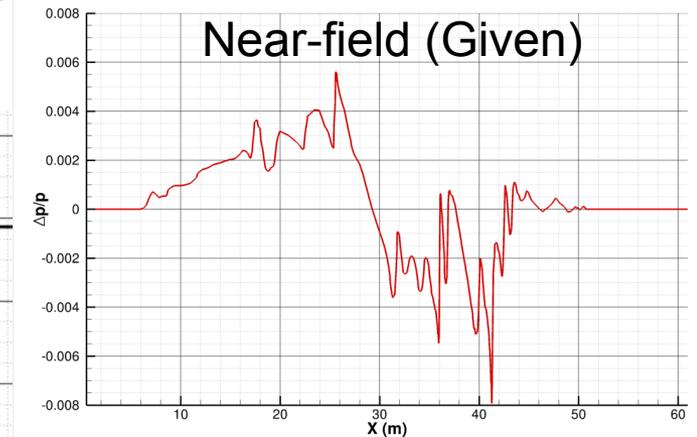
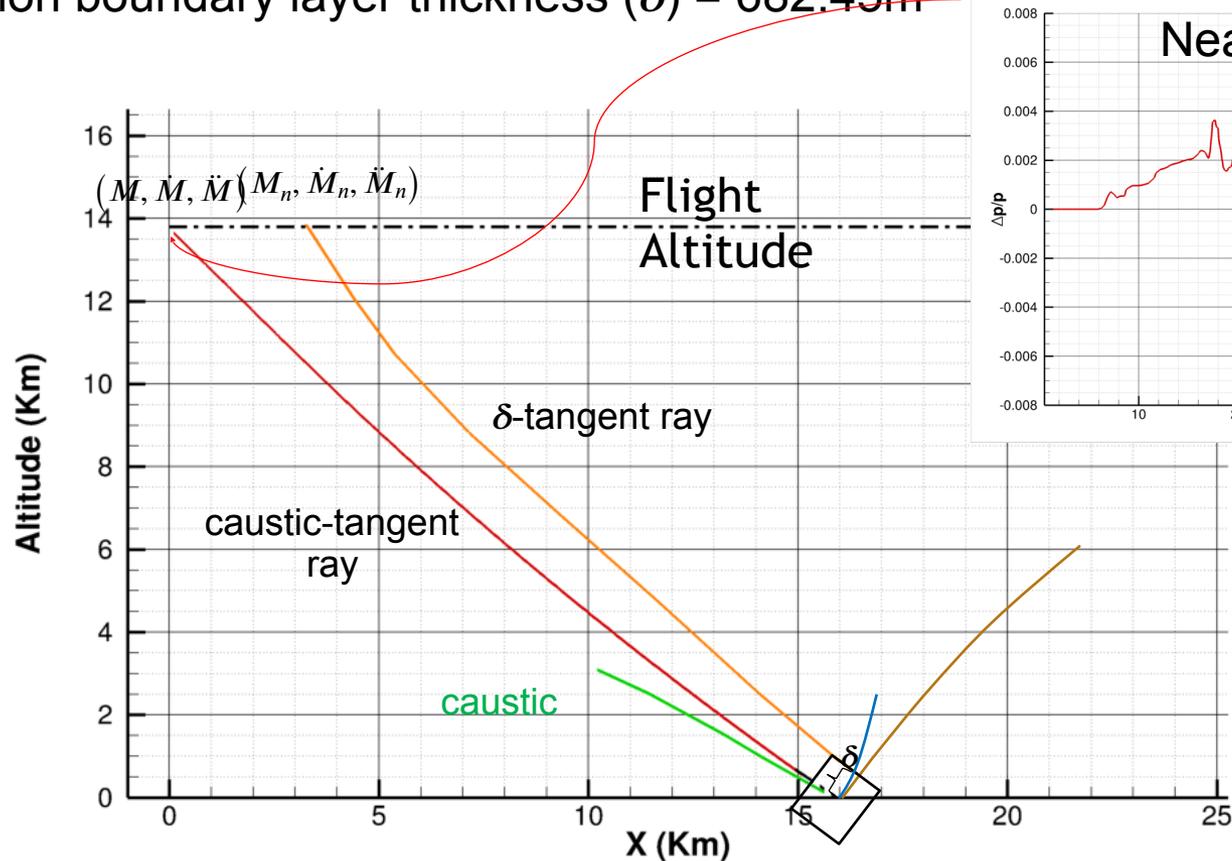
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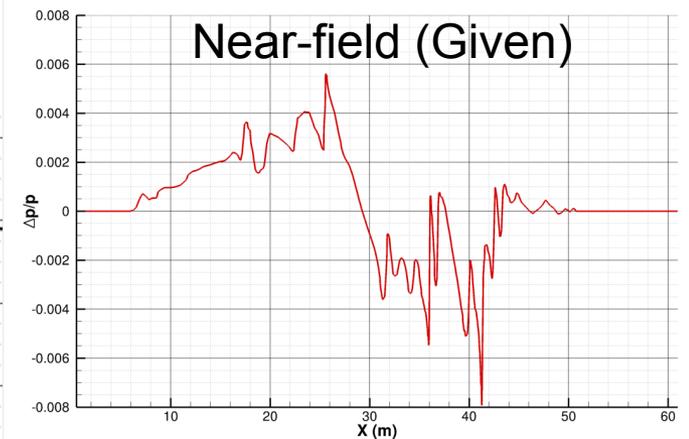
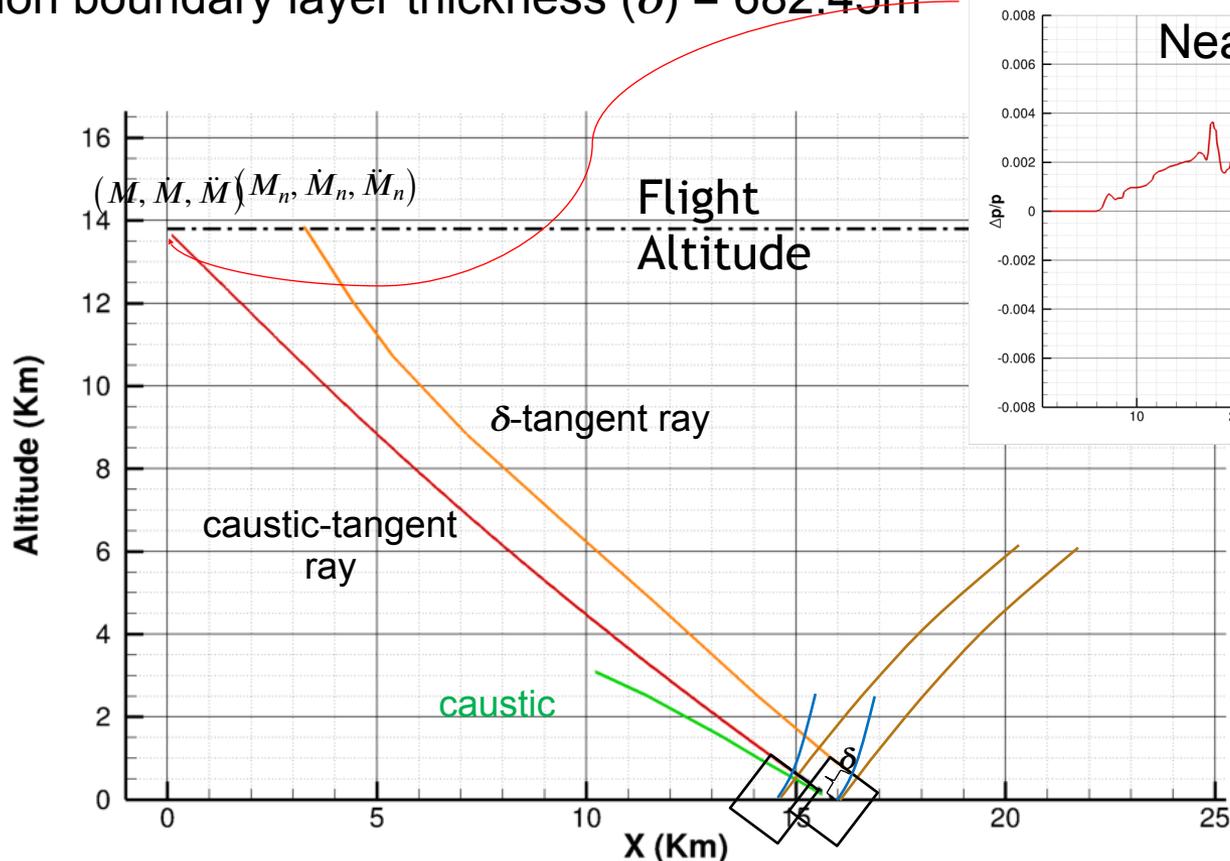
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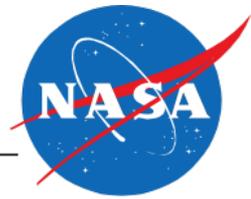


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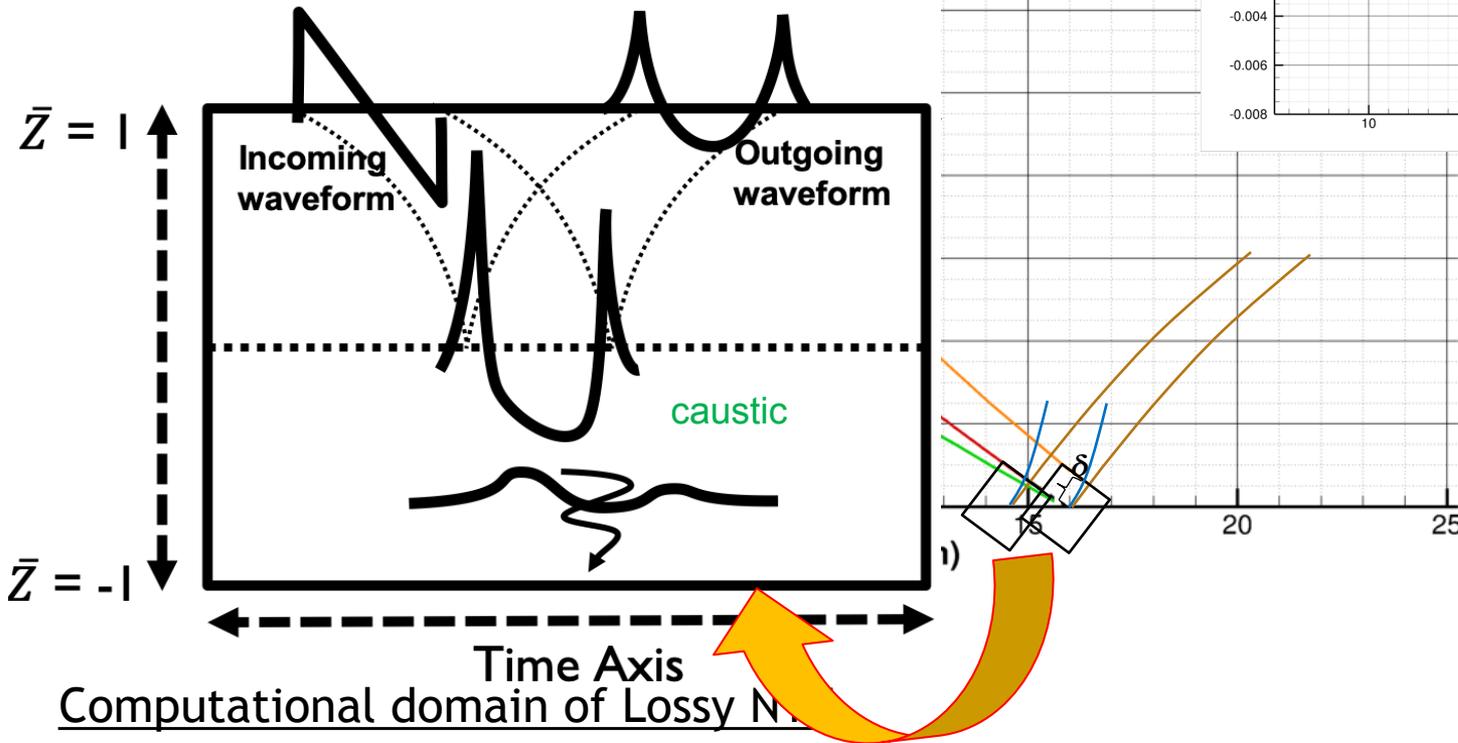
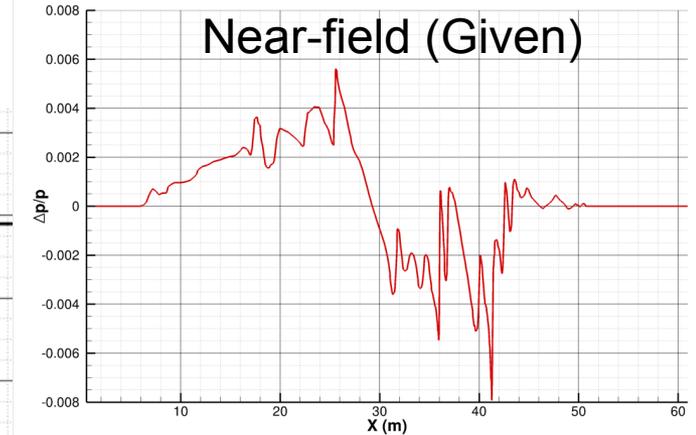
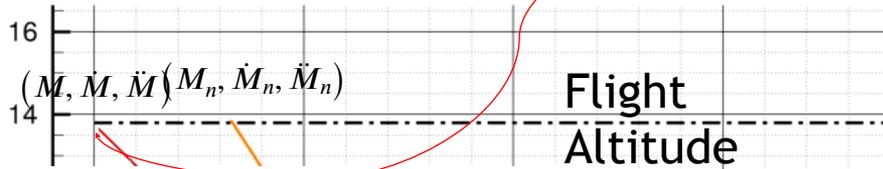
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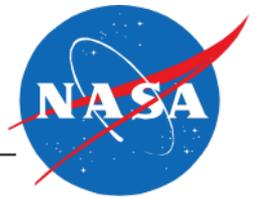


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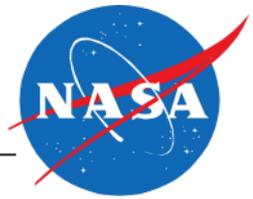


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Lossy NTE Model Equation as developed by Joe Salamone for the NASA Scamp Project

$$\mu = 2\beta \frac{P_{ac}}{\rho_0 c_0^2} \left( \frac{R_{tot} f_{ac}}{2c_0} \right)^{2/3} \quad \epsilon = \left( \frac{2c_0}{R_{tot} f_{ac}} \right)^{2/3} \quad R_{tot} \approx R_{cau} = \frac{2\delta^3 f_{ac}^2}{c_0^2}$$

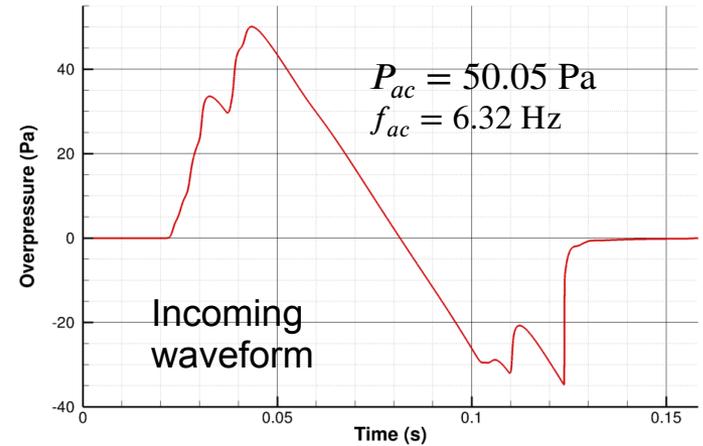
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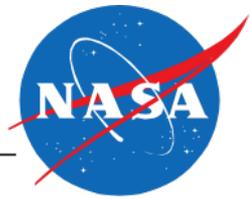
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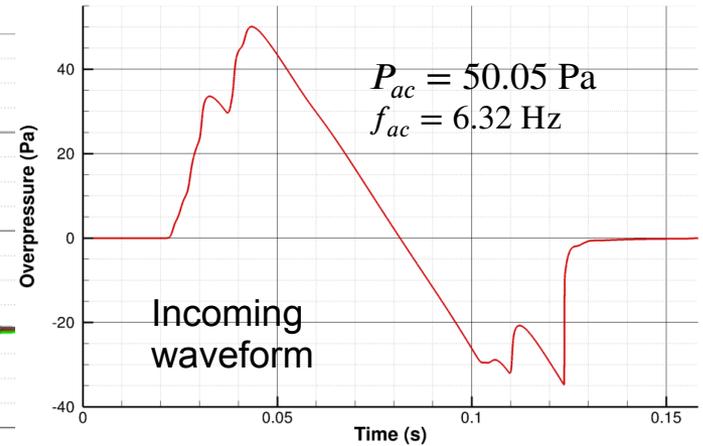
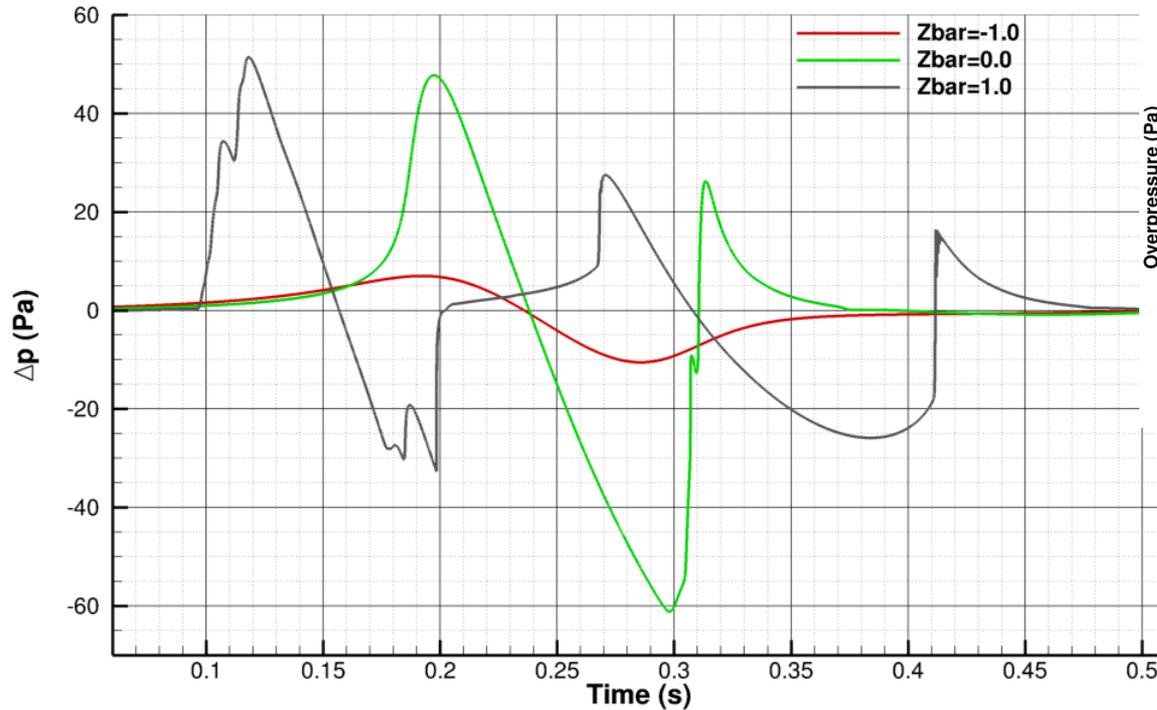
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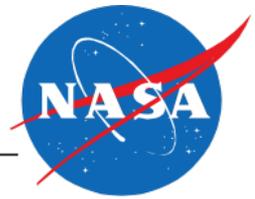


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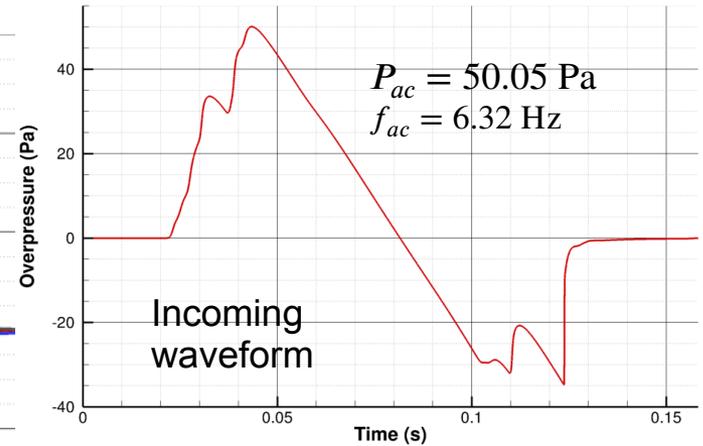
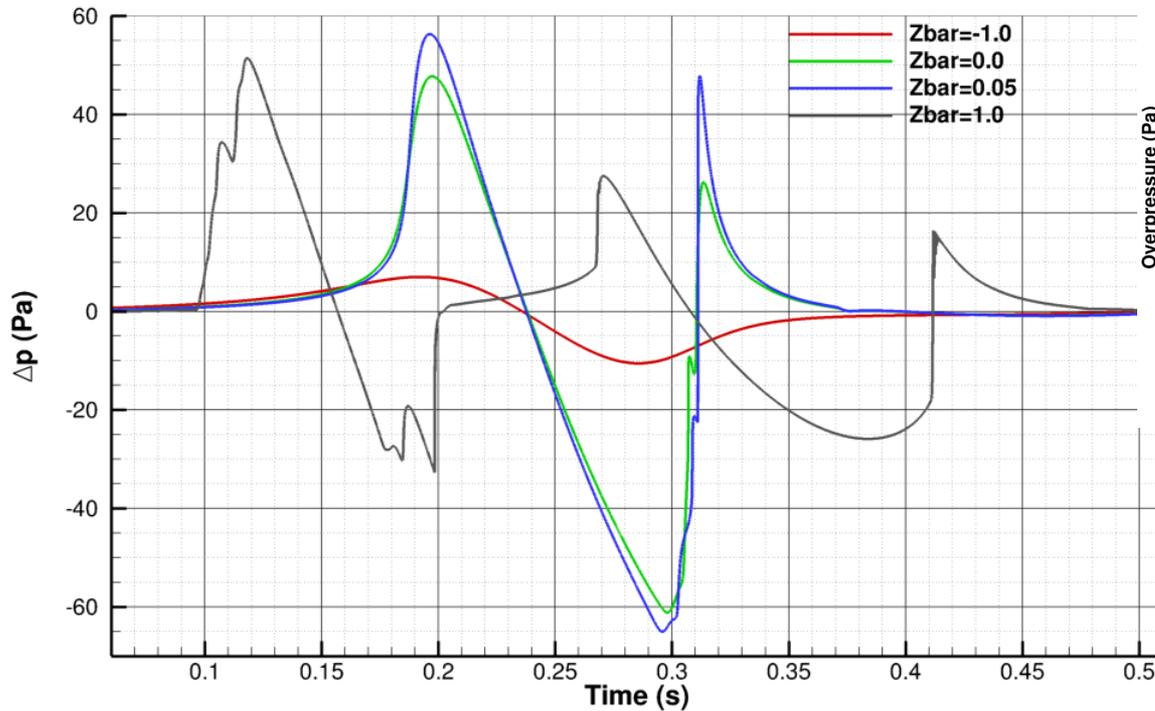


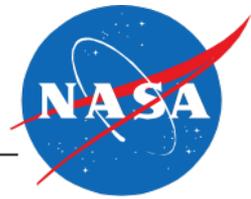
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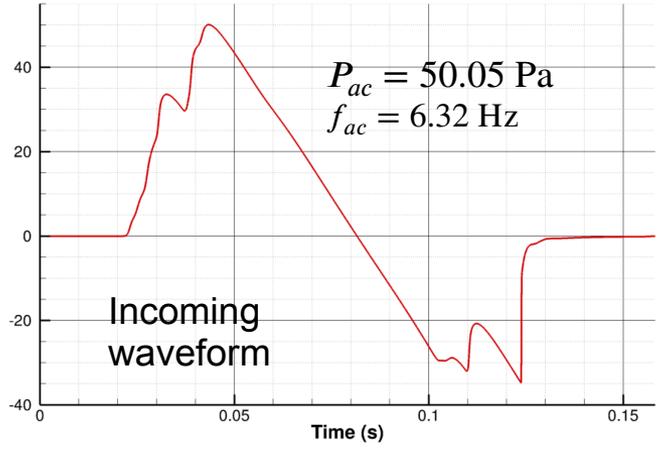
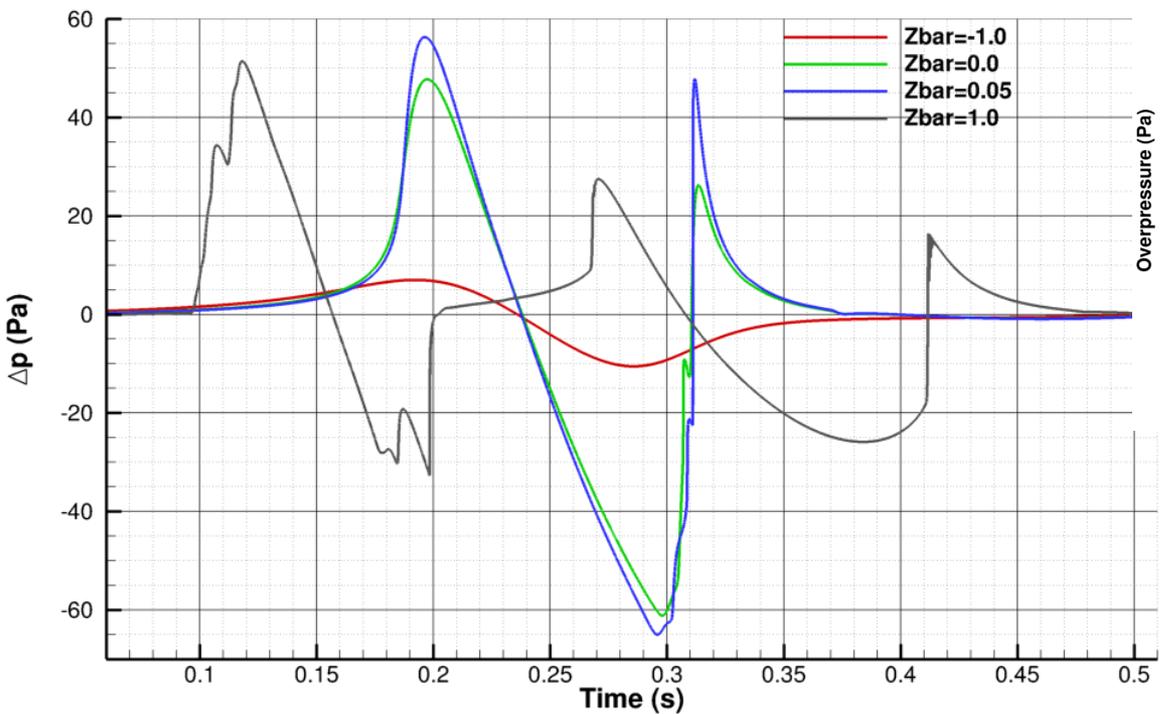


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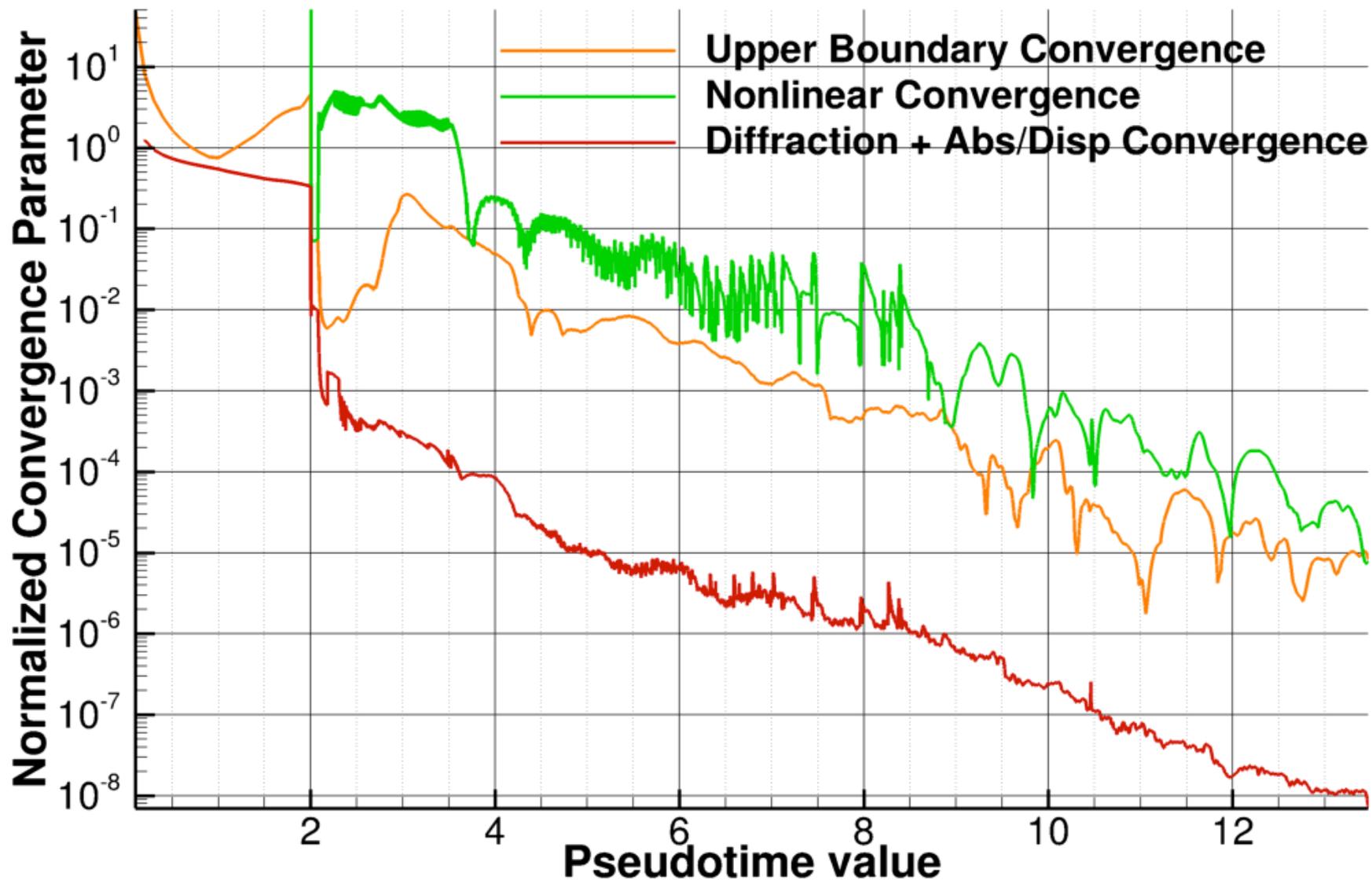
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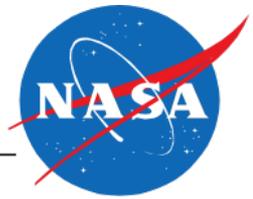
- Zbar=0.0: PL = 97.8 dB
- Zbar=0.05: PL = 106.8 dB
- Zbar=1.0: PL = 101.0 dB

# Case1: Optional Focus Analysis



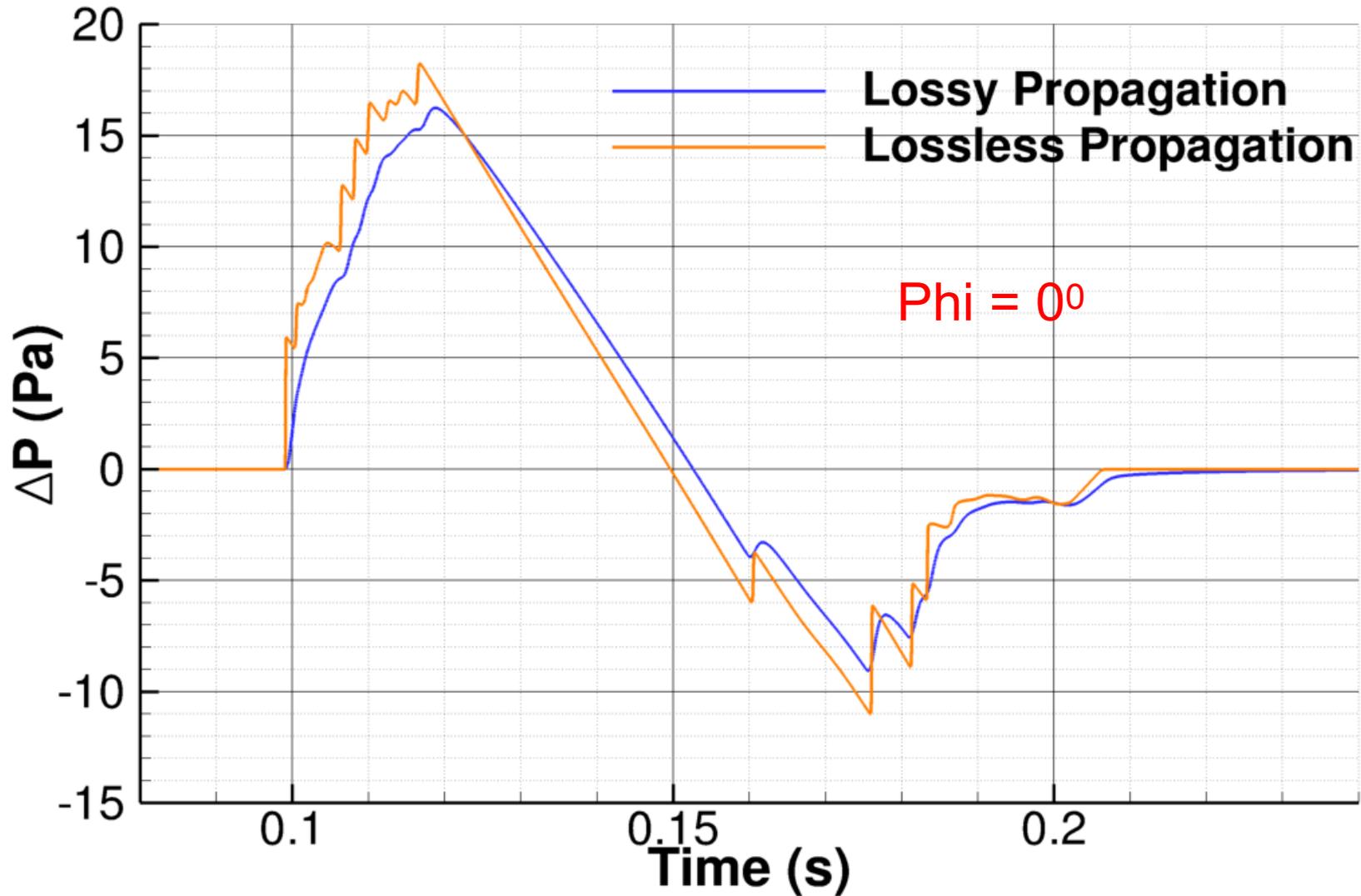
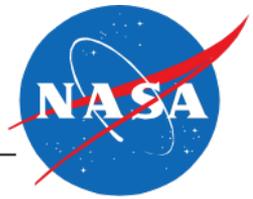
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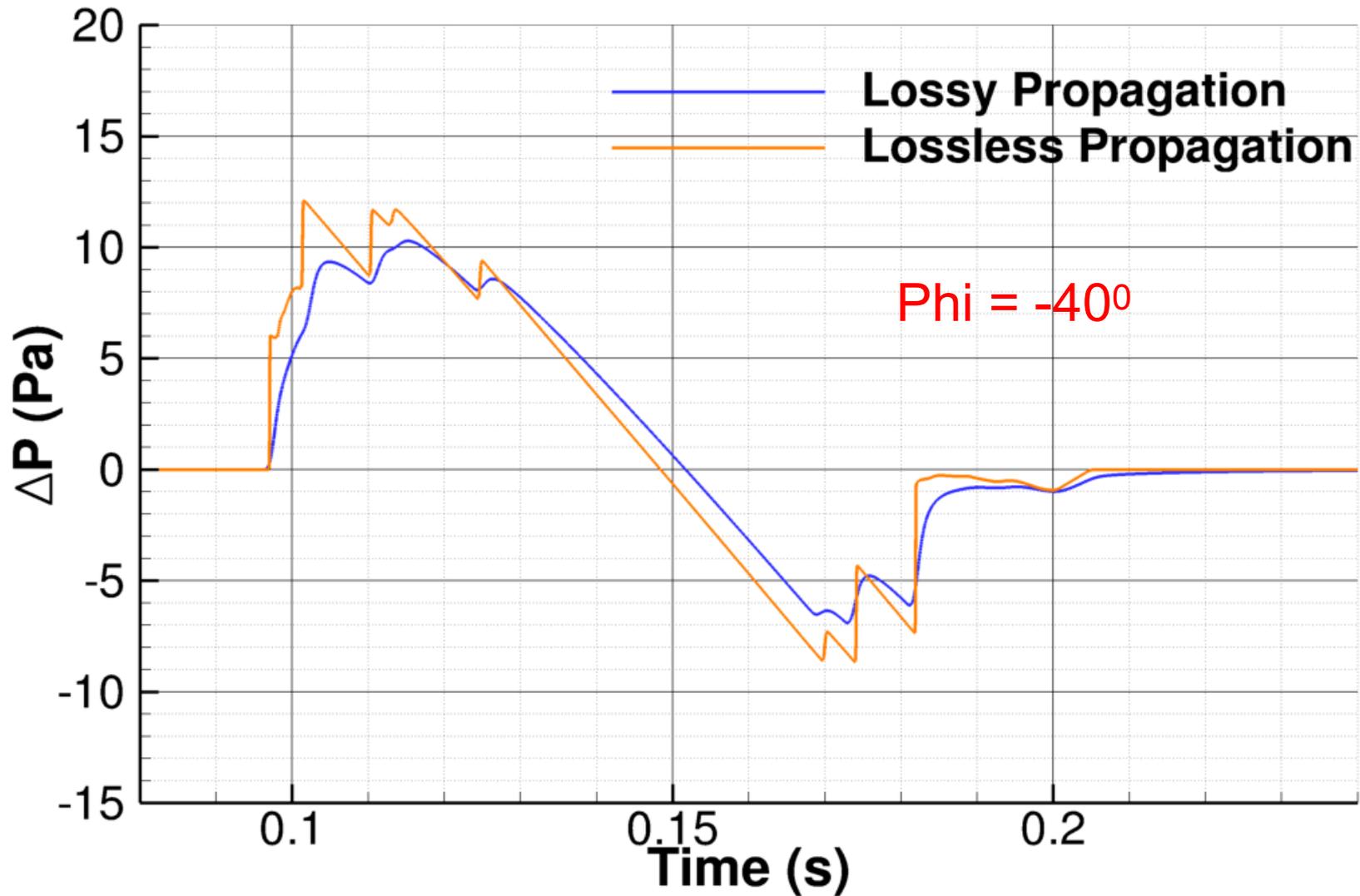
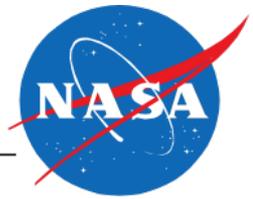


- Lossy vs Lossless propagation
- Signature Evolution
- Modeling Non-linearity
- Loudness build-ups
- Loudness Gradients

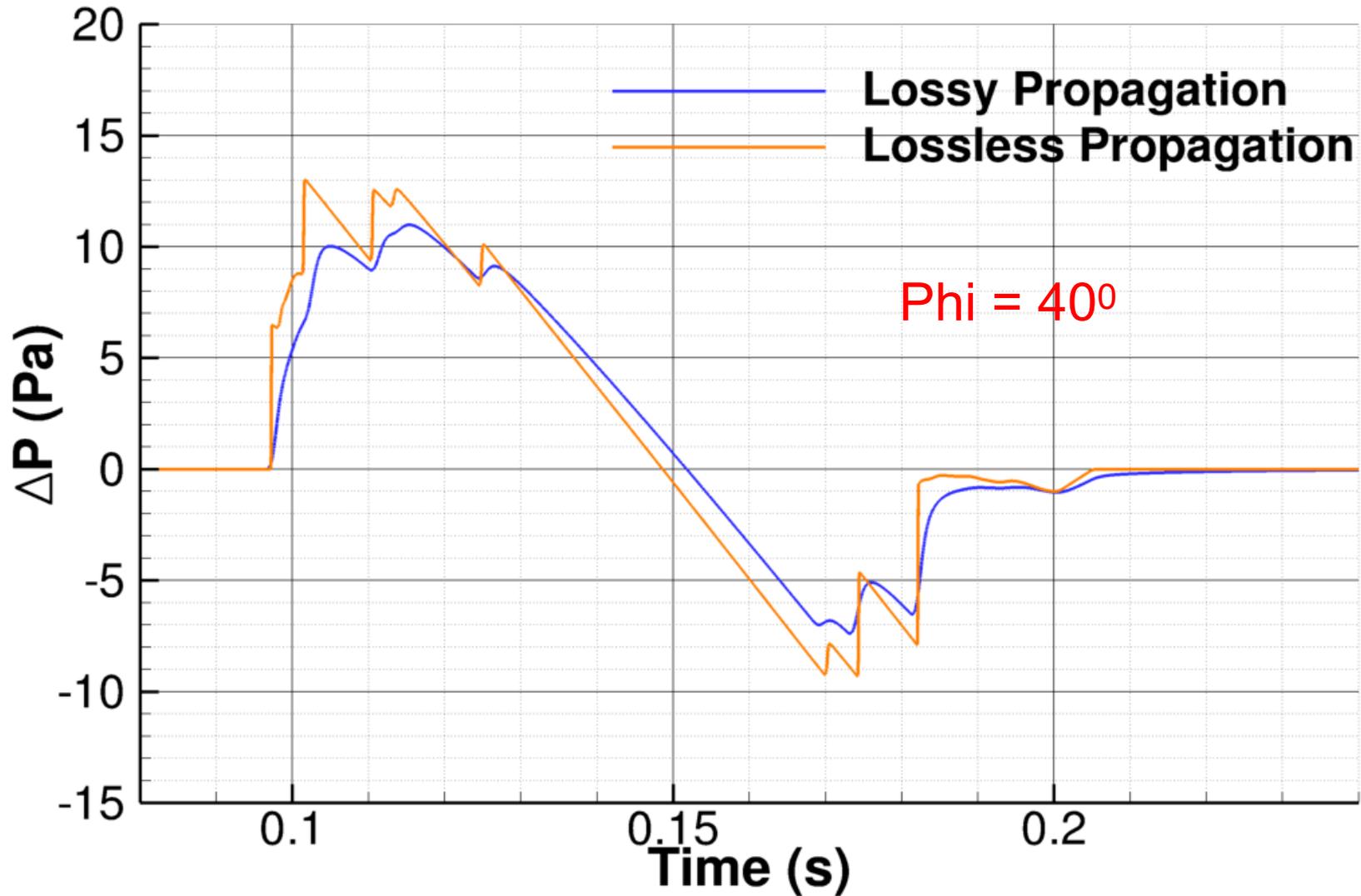
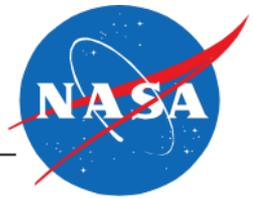
# Highlights: Lossless vs Lossy



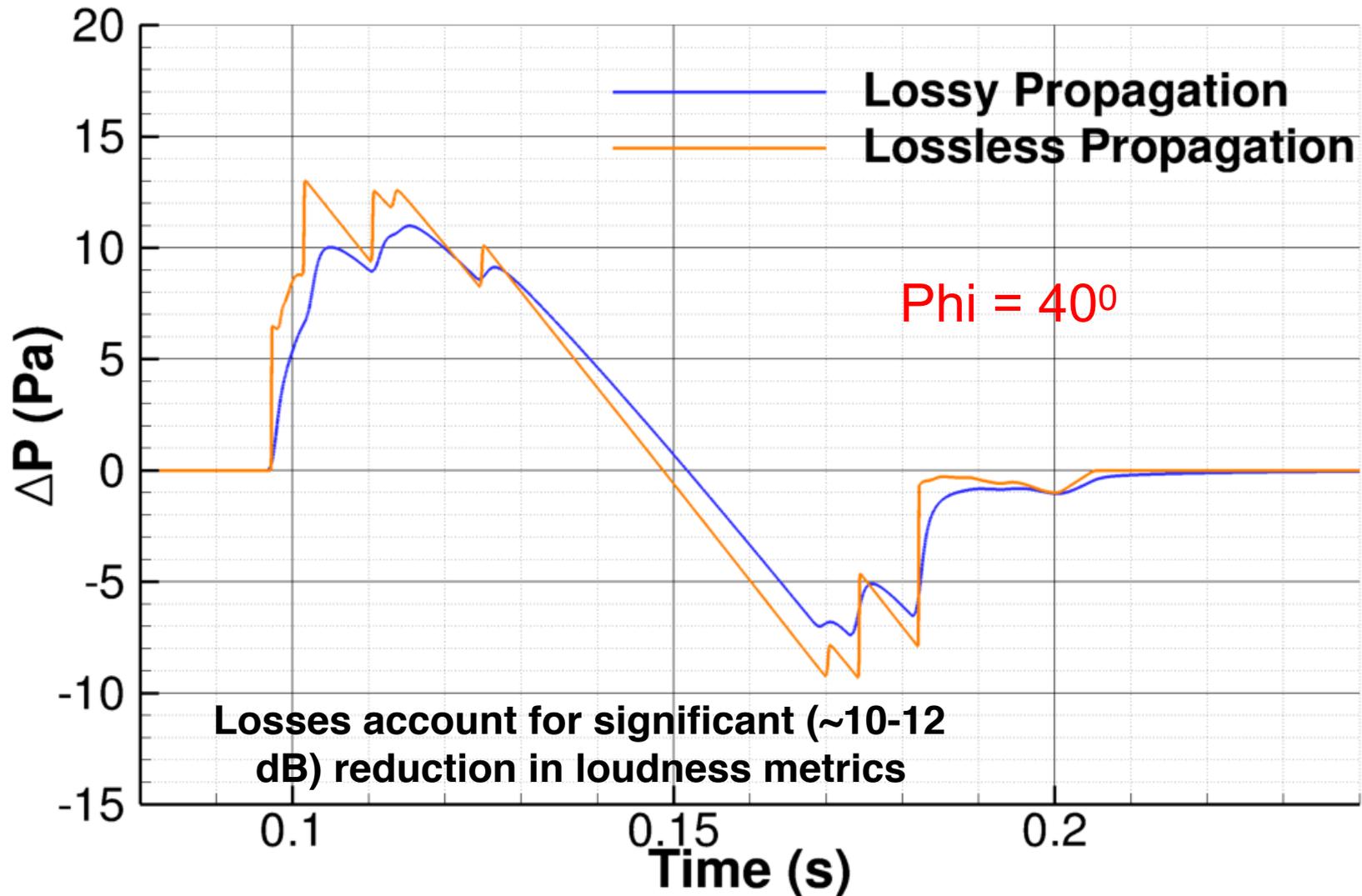
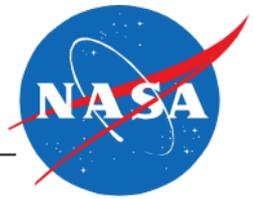
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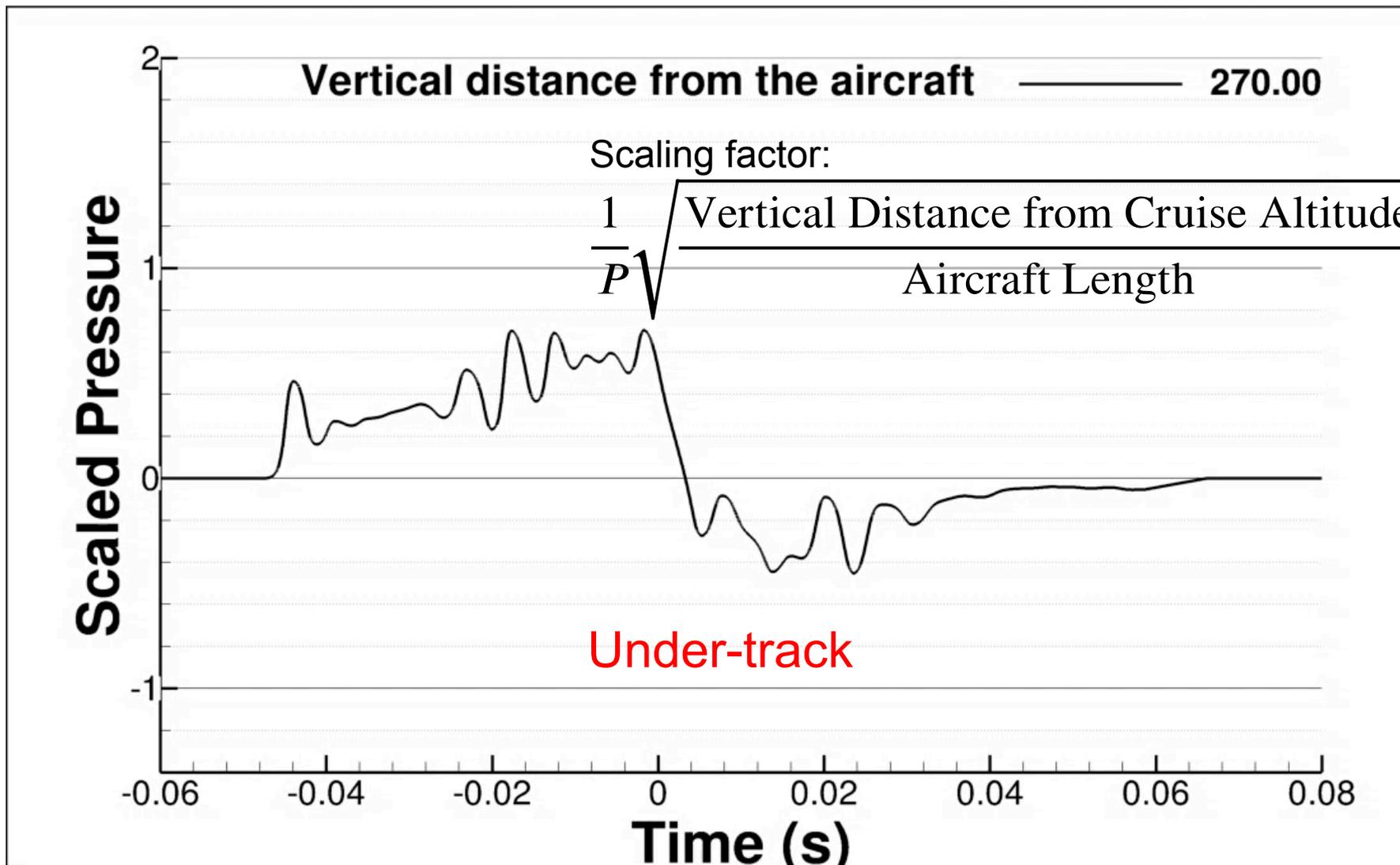
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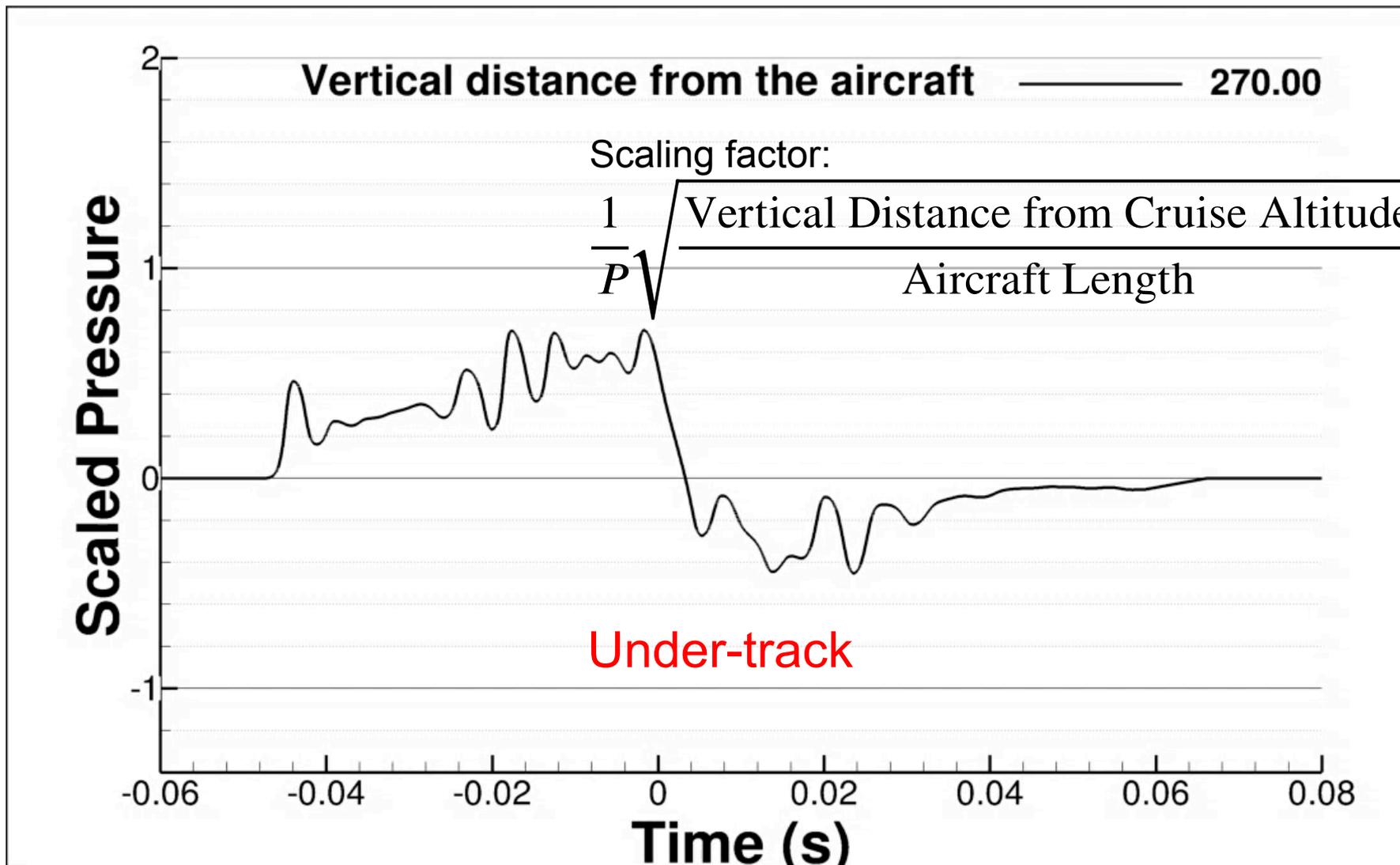
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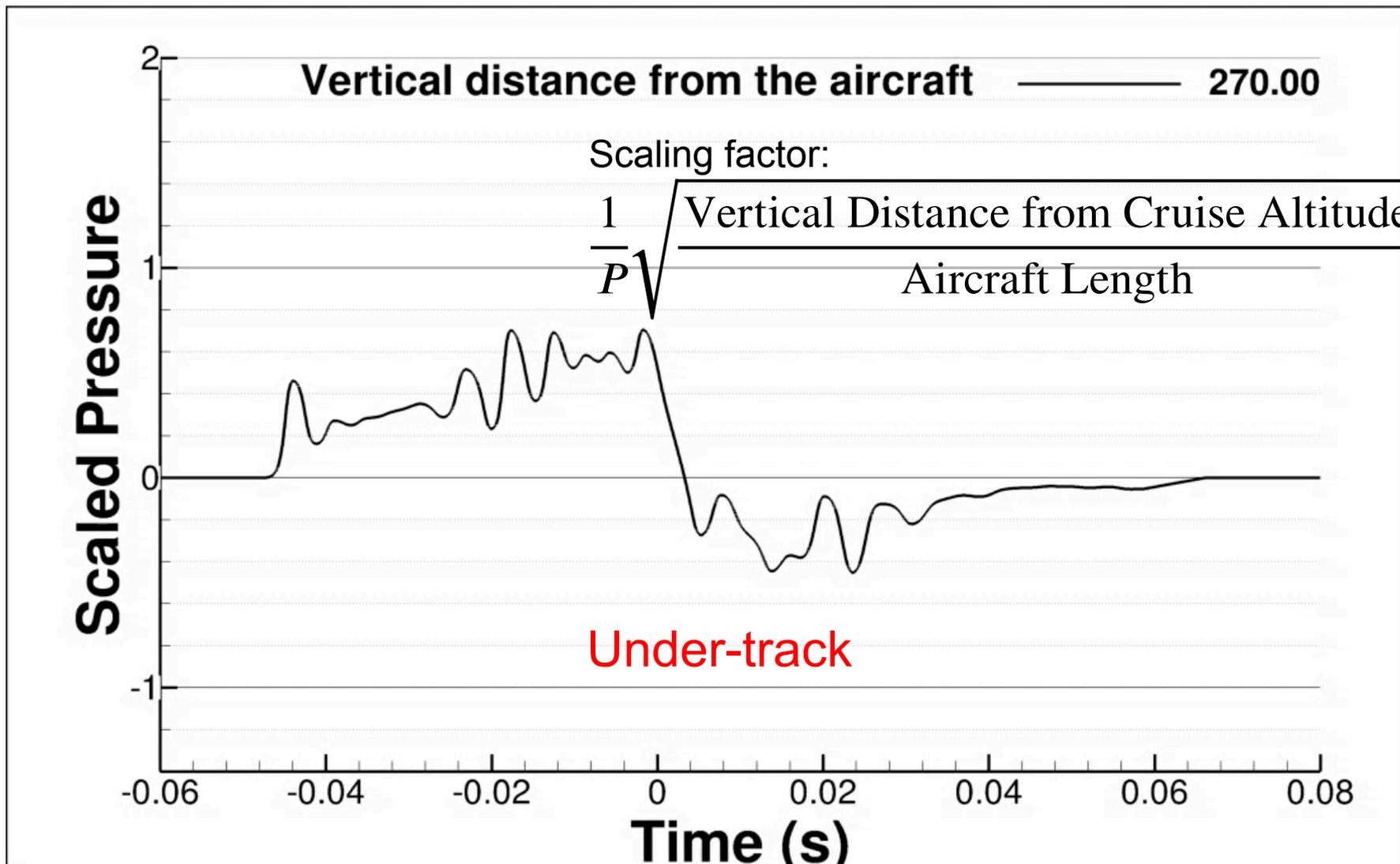
# Highlights: Signature Evolution



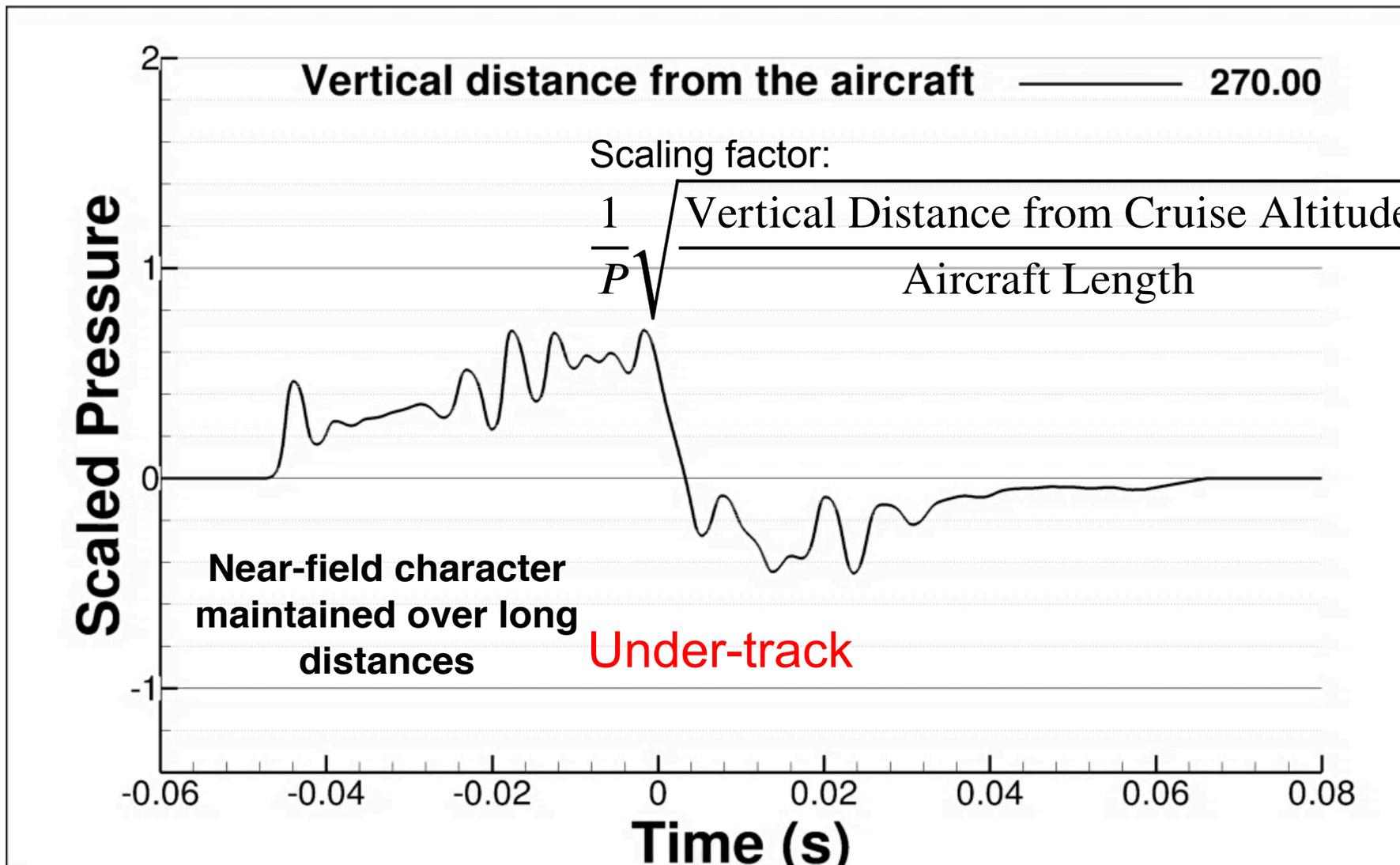
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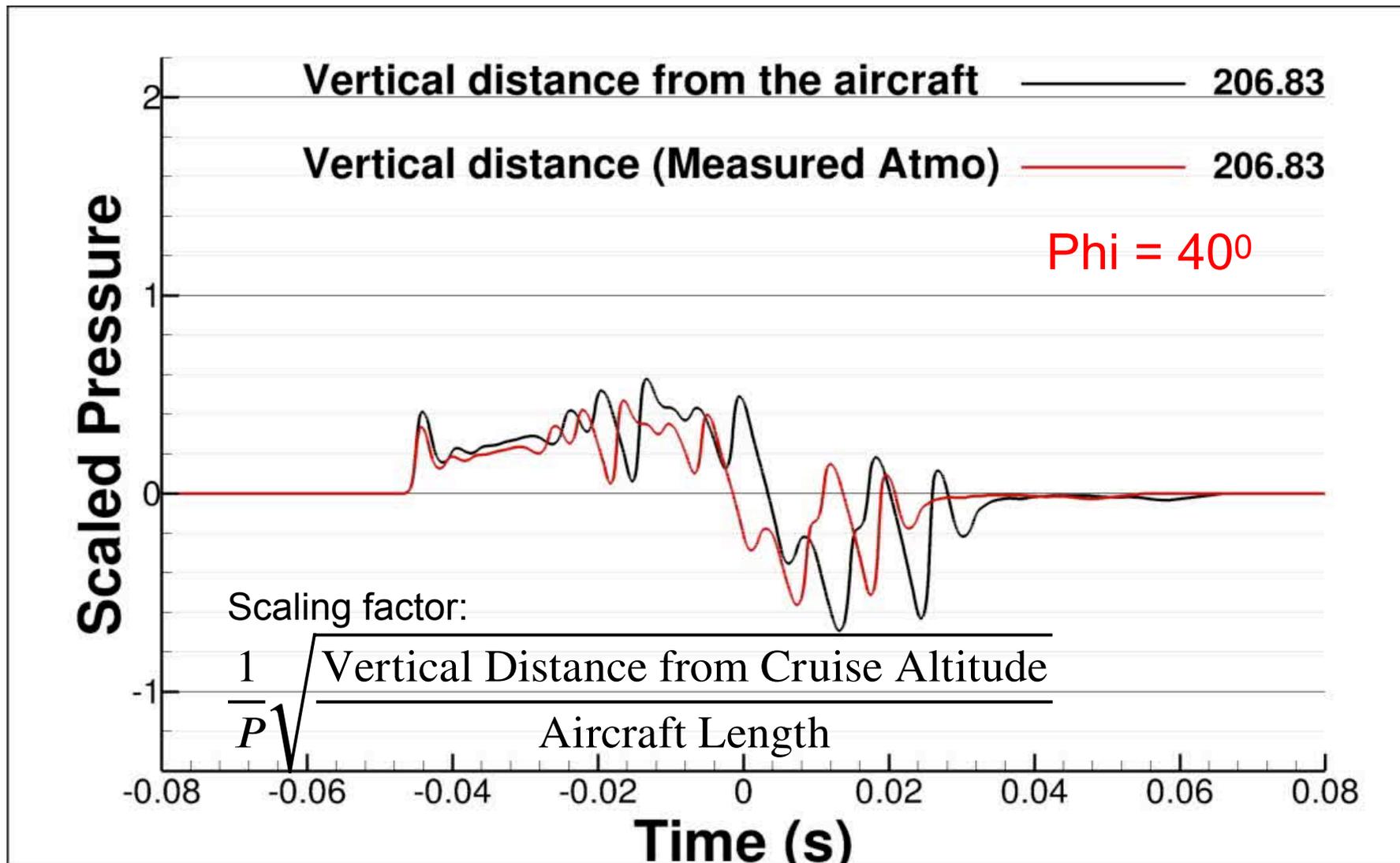
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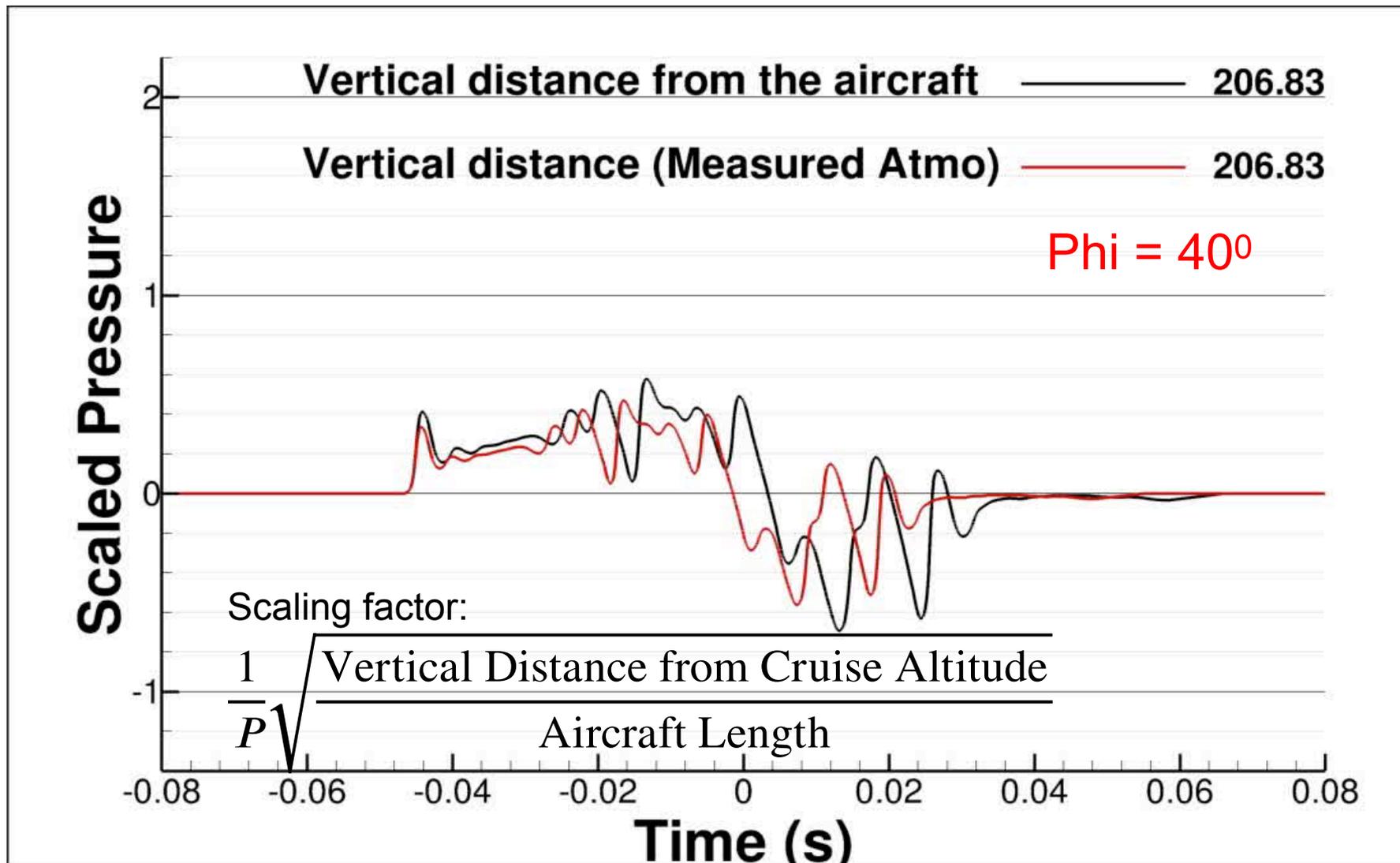
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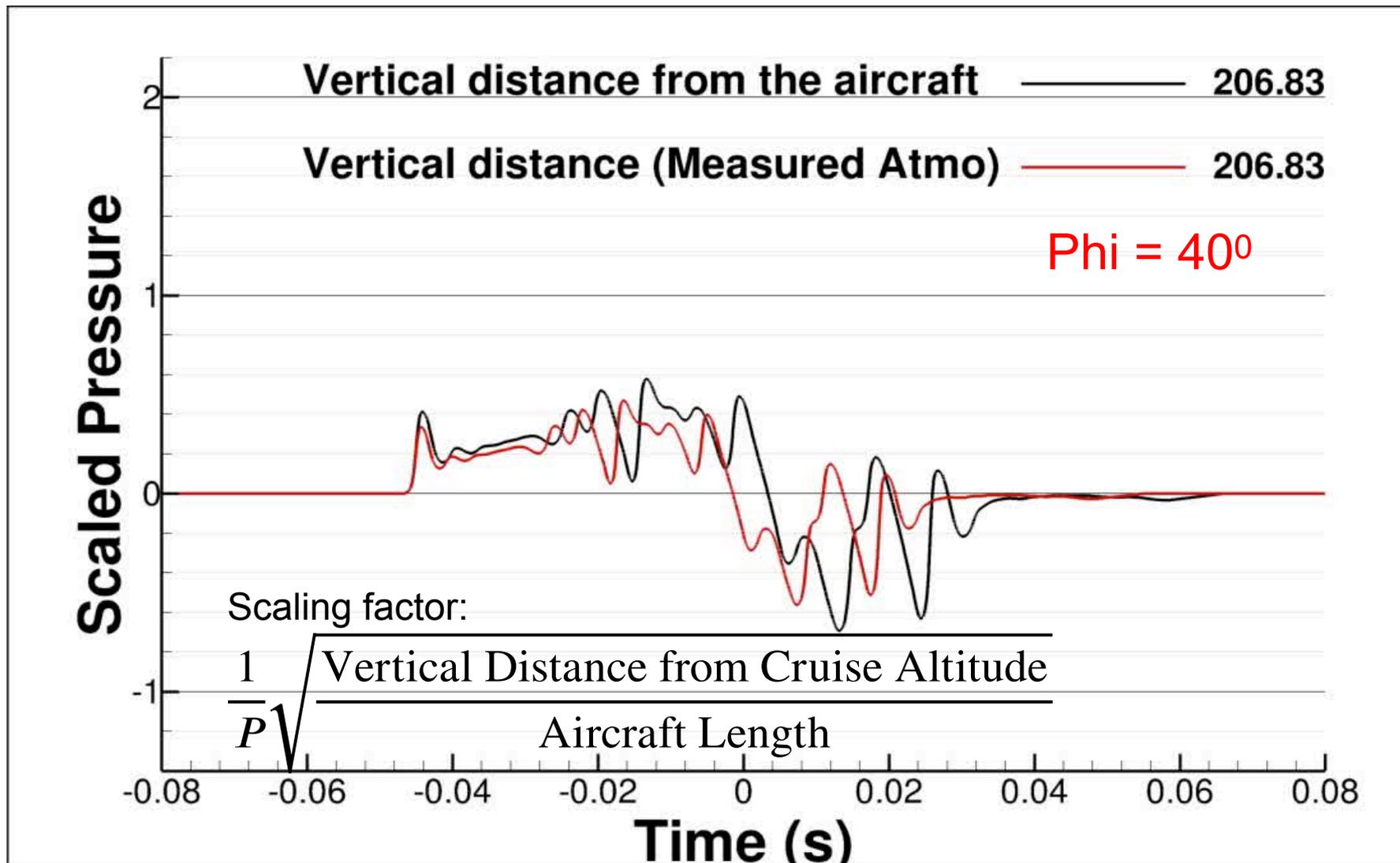
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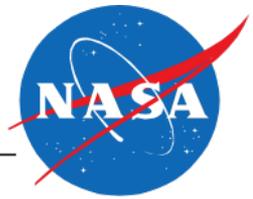


# Highlights: Signature Evolution



# Highlights: Modeling Non-linearity

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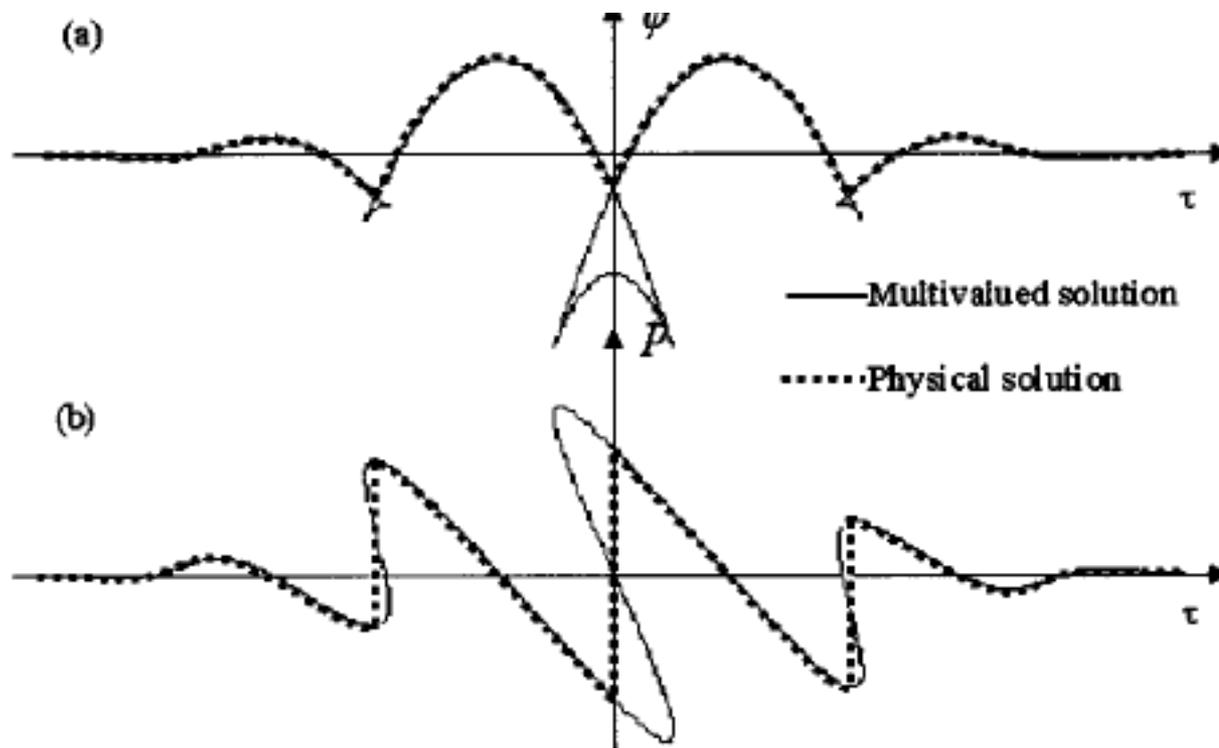
Acoustic Potential formulation vs Poisson Implementation

# Highlights: Modeling Non-linearity



## Acoustic Potential formulation vs Poisson Implementation

$$\phi(t, \tau) = \phi_0(\theta) - \frac{\mu t}{2} (p_0(\theta))^2.$$
$$\phi(t, \tau) = \max \left\{ \phi_0(\theta) - \frac{\mu t}{2} (p_0(\theta))^2 \right\}.$$

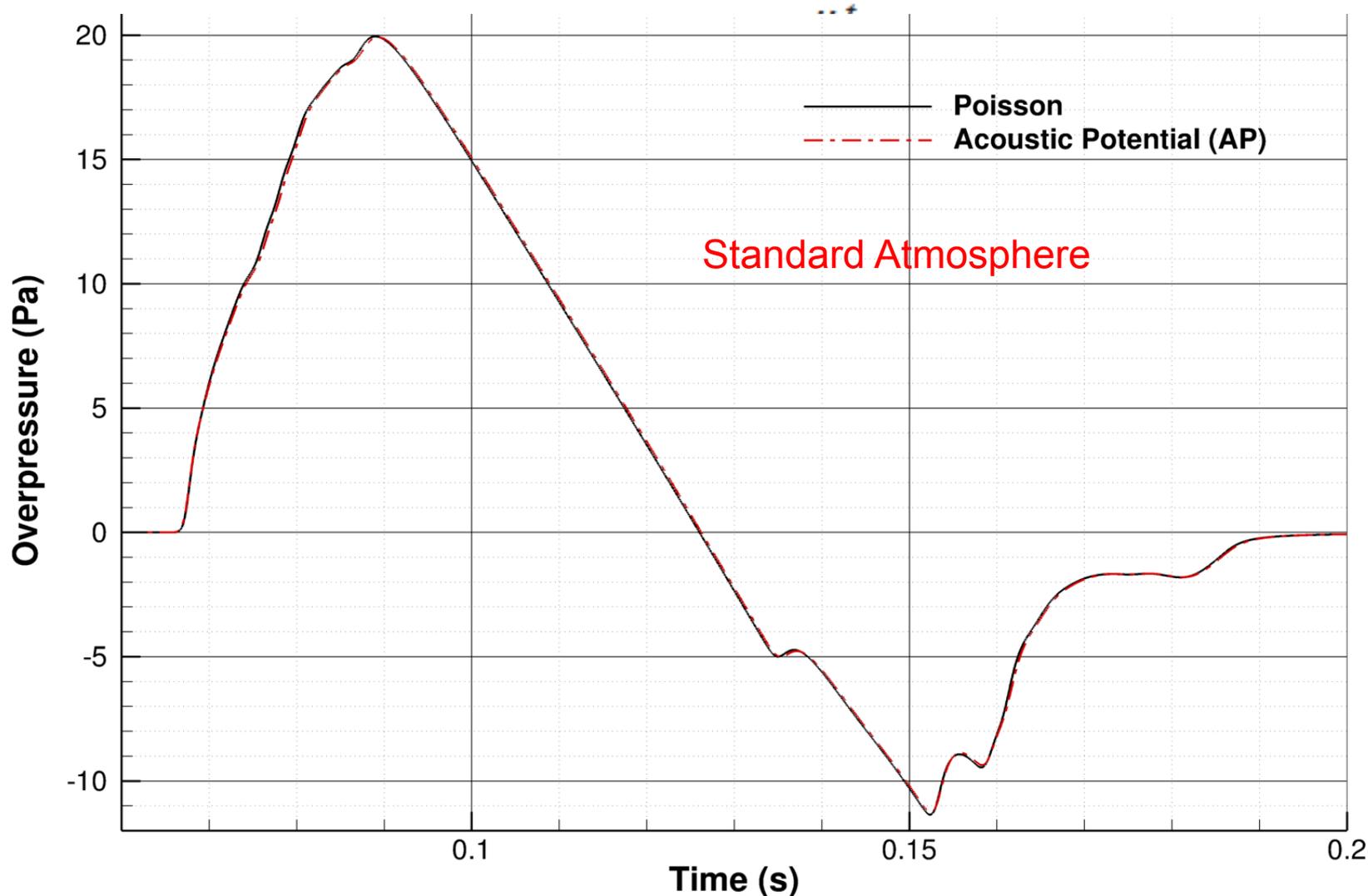


“Numerical Simulation of Shock Wave Focusing at Fold Caustics, with application to Sonic Boom”, Marchiano, R., Coulouvrat, F., Grenon, R., JASA, 114, 1758 (2003), doi: 10.1121/1.1610459

# Highlights: Modeling Non-linearity



## Acoustic Potential formulation vs Poisson Implementation

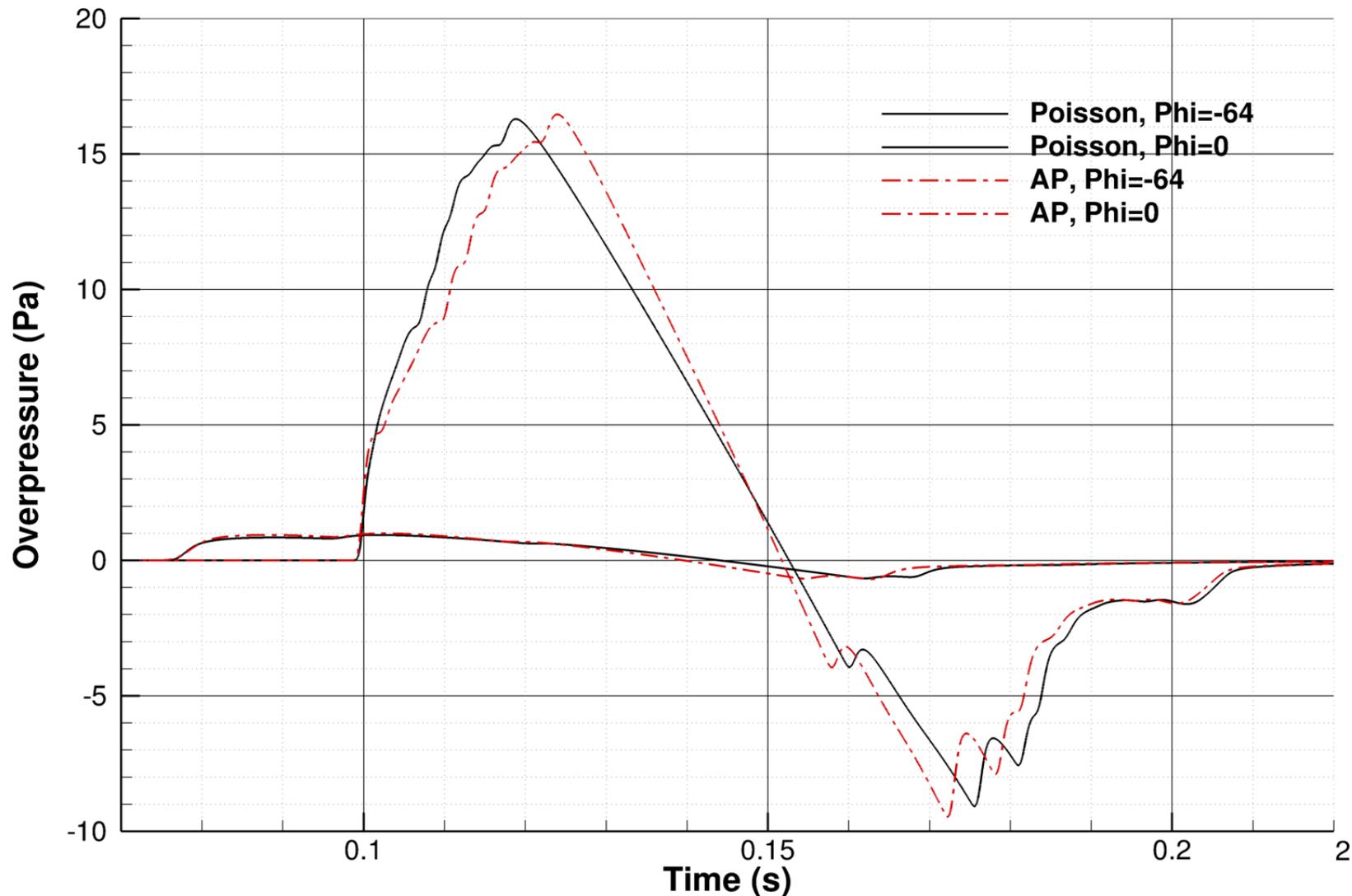


Coulouvrat, F., Grenon, R., JASA, 114, 1758 (2003), doi: 10.1121/1.1610459

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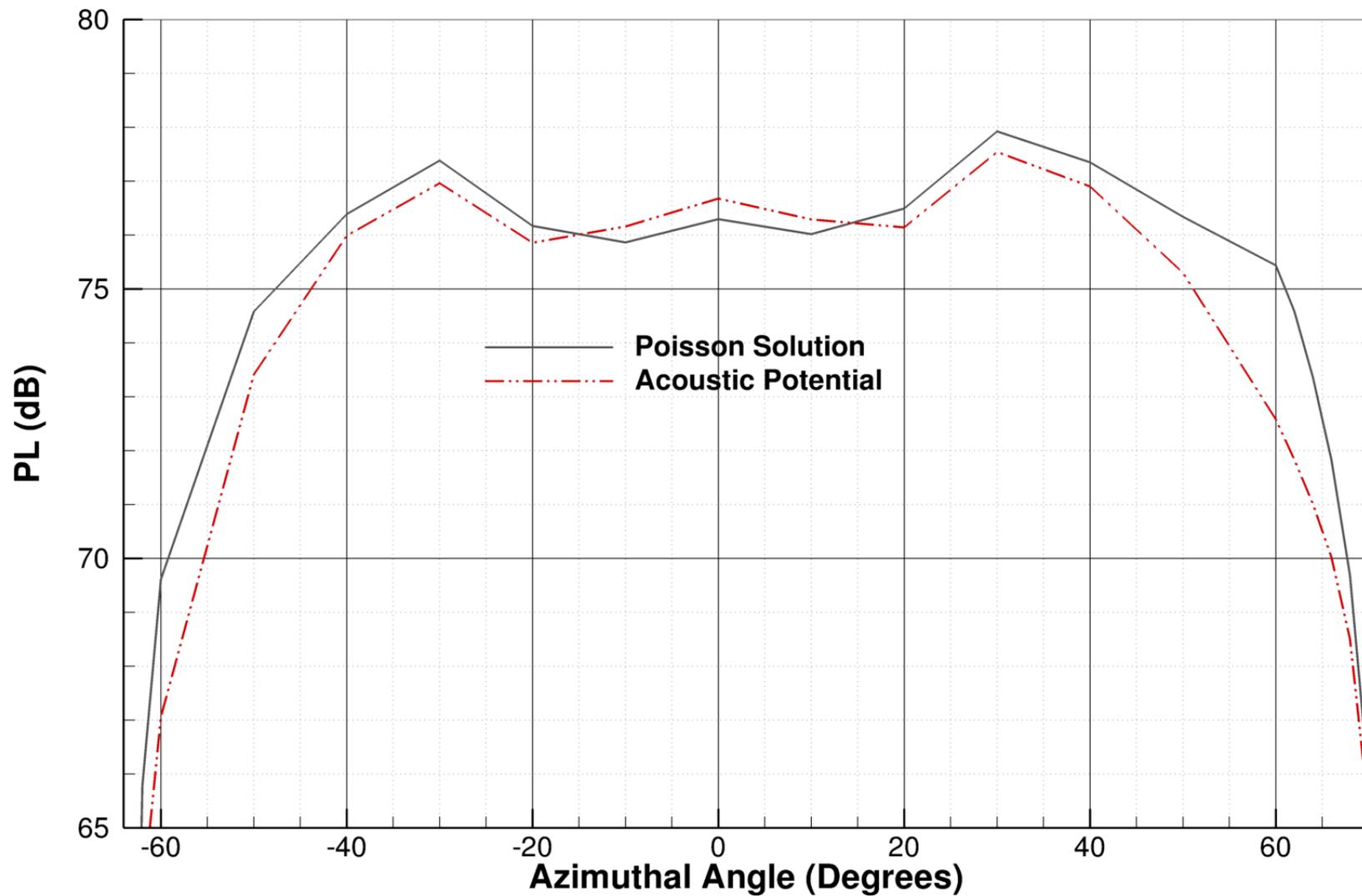


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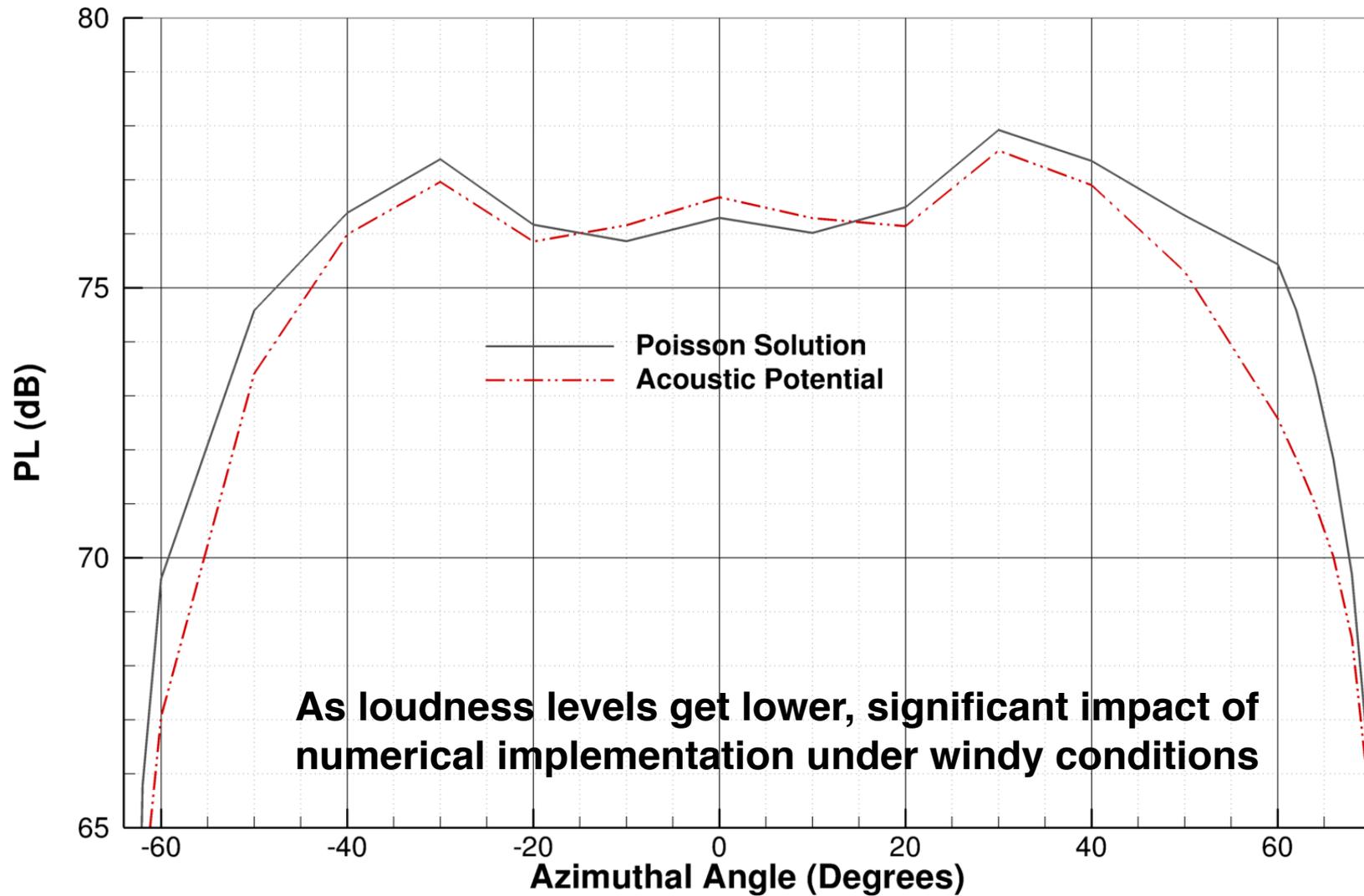


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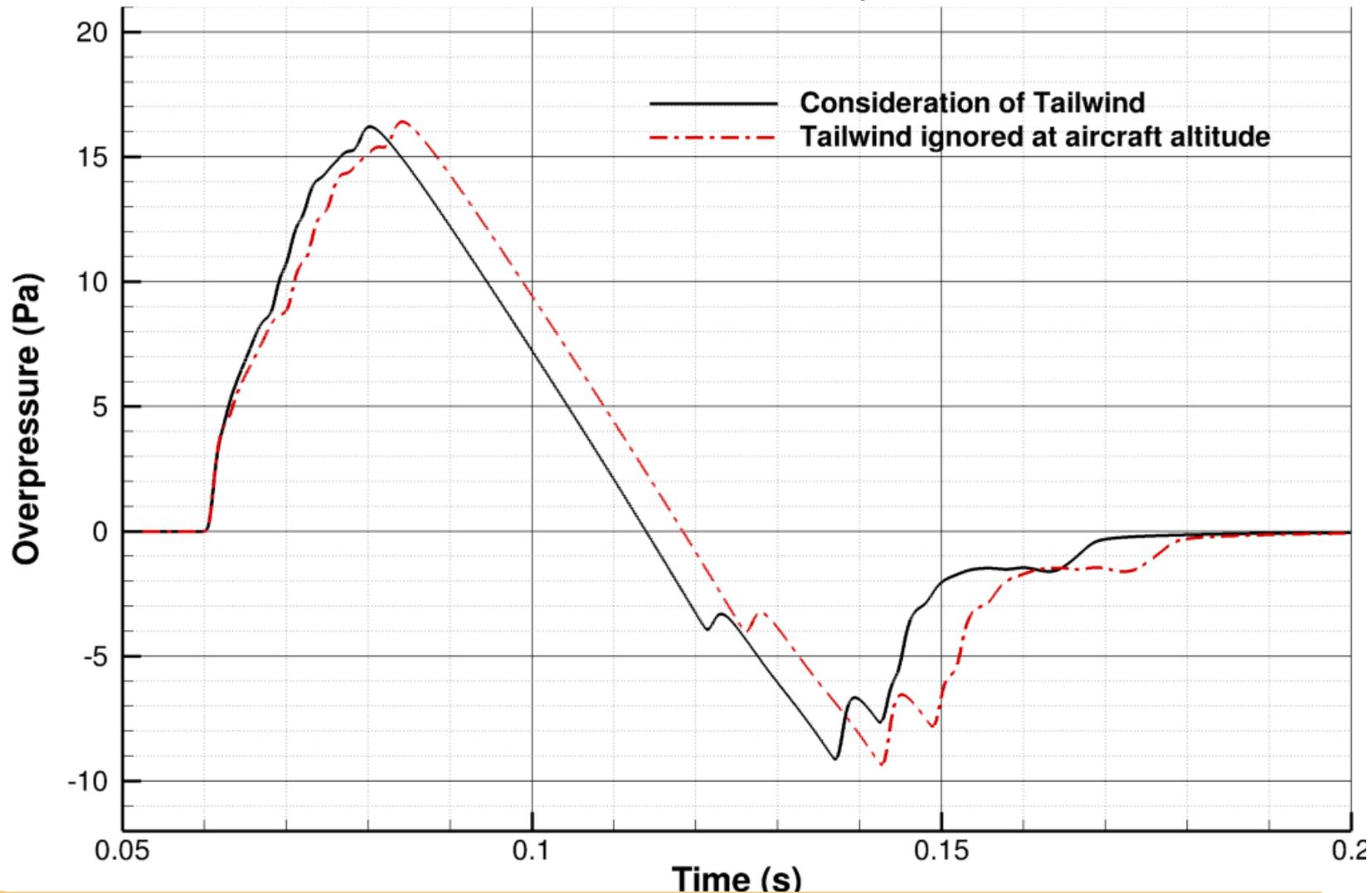


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# Highlights: Modeling Wind



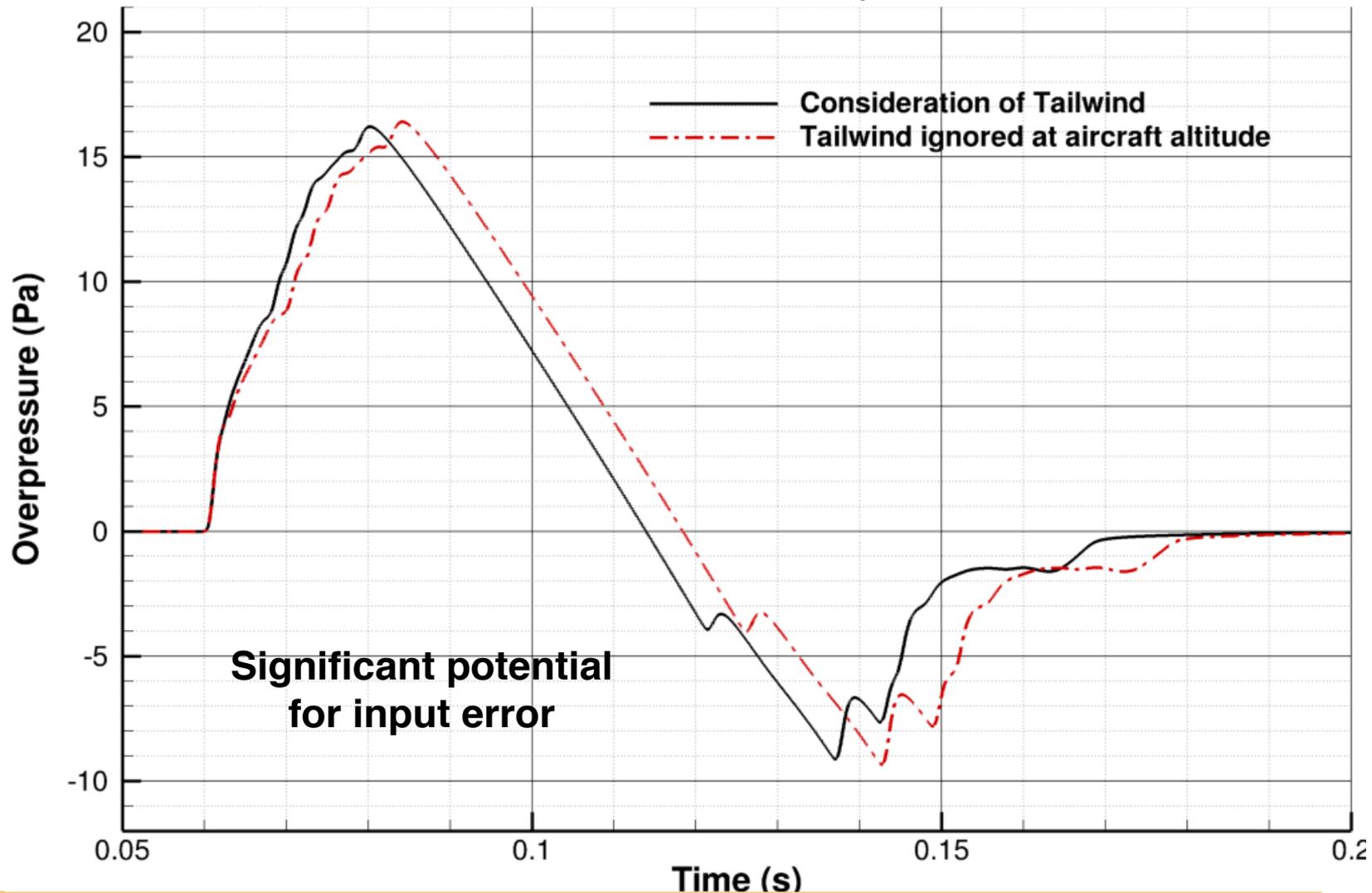
- Based on provided data, there is a large tailwind at the cruise altitude
  - Tailwind accounts for almost 10% of the speed of sound



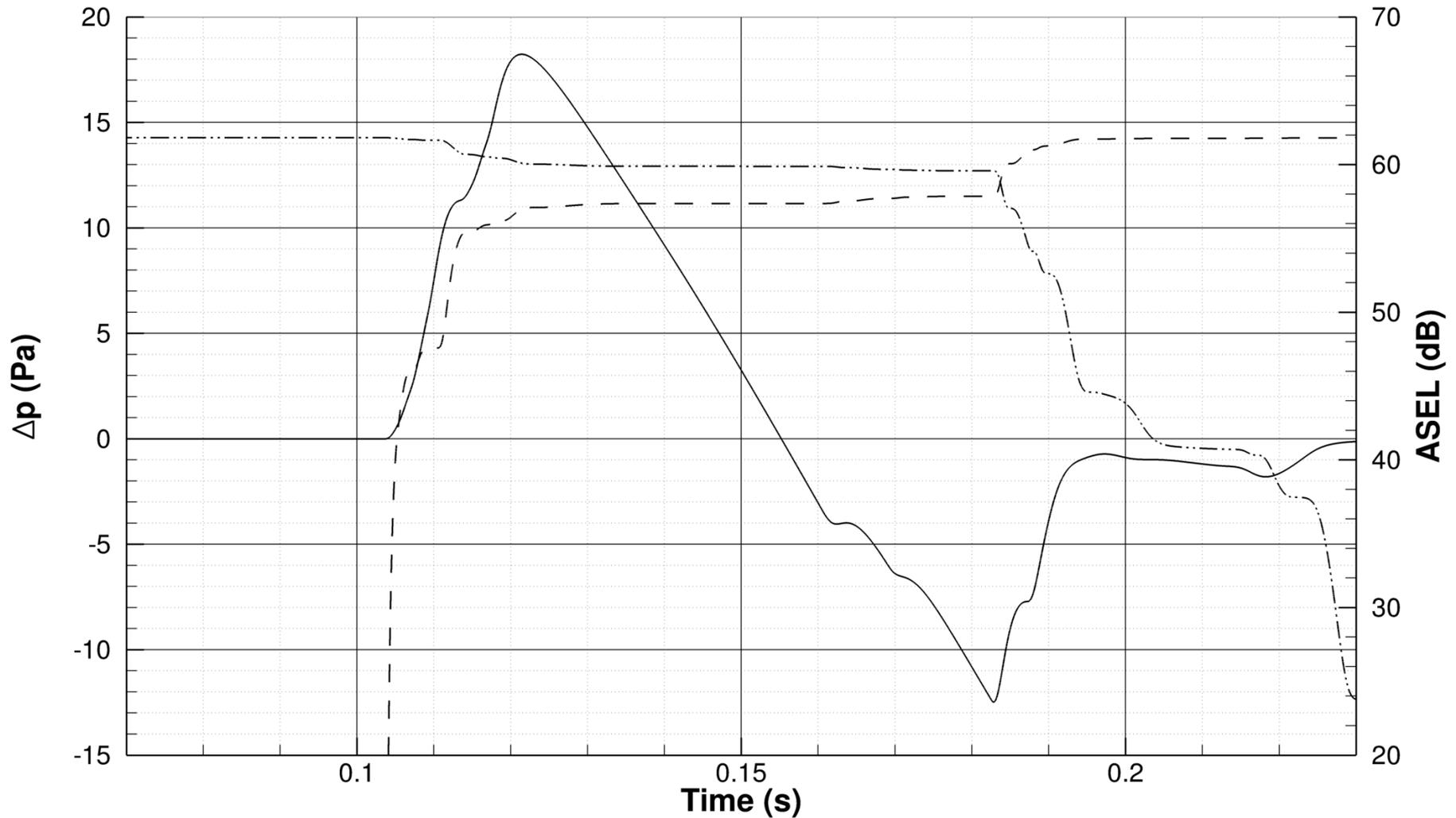
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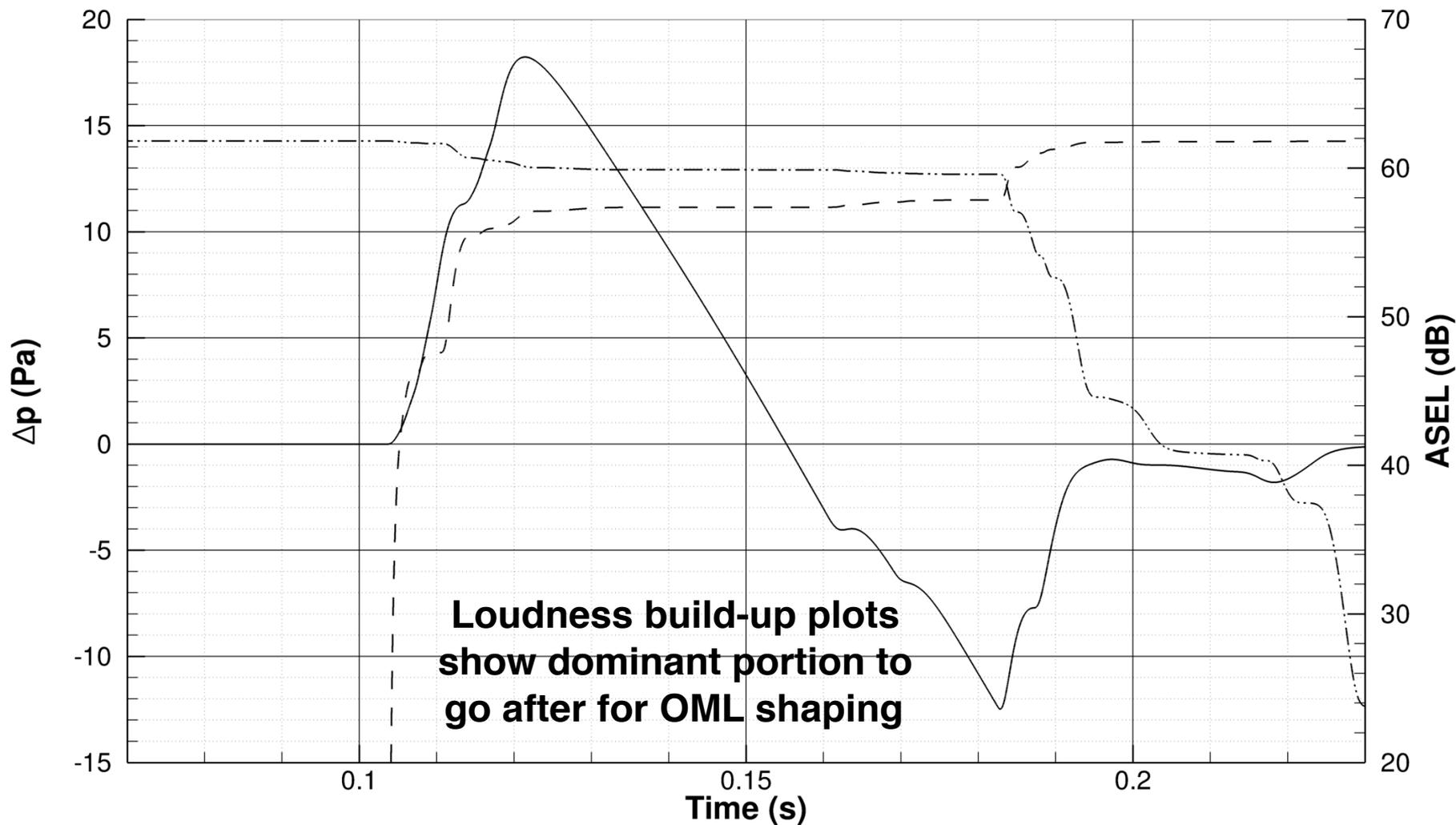
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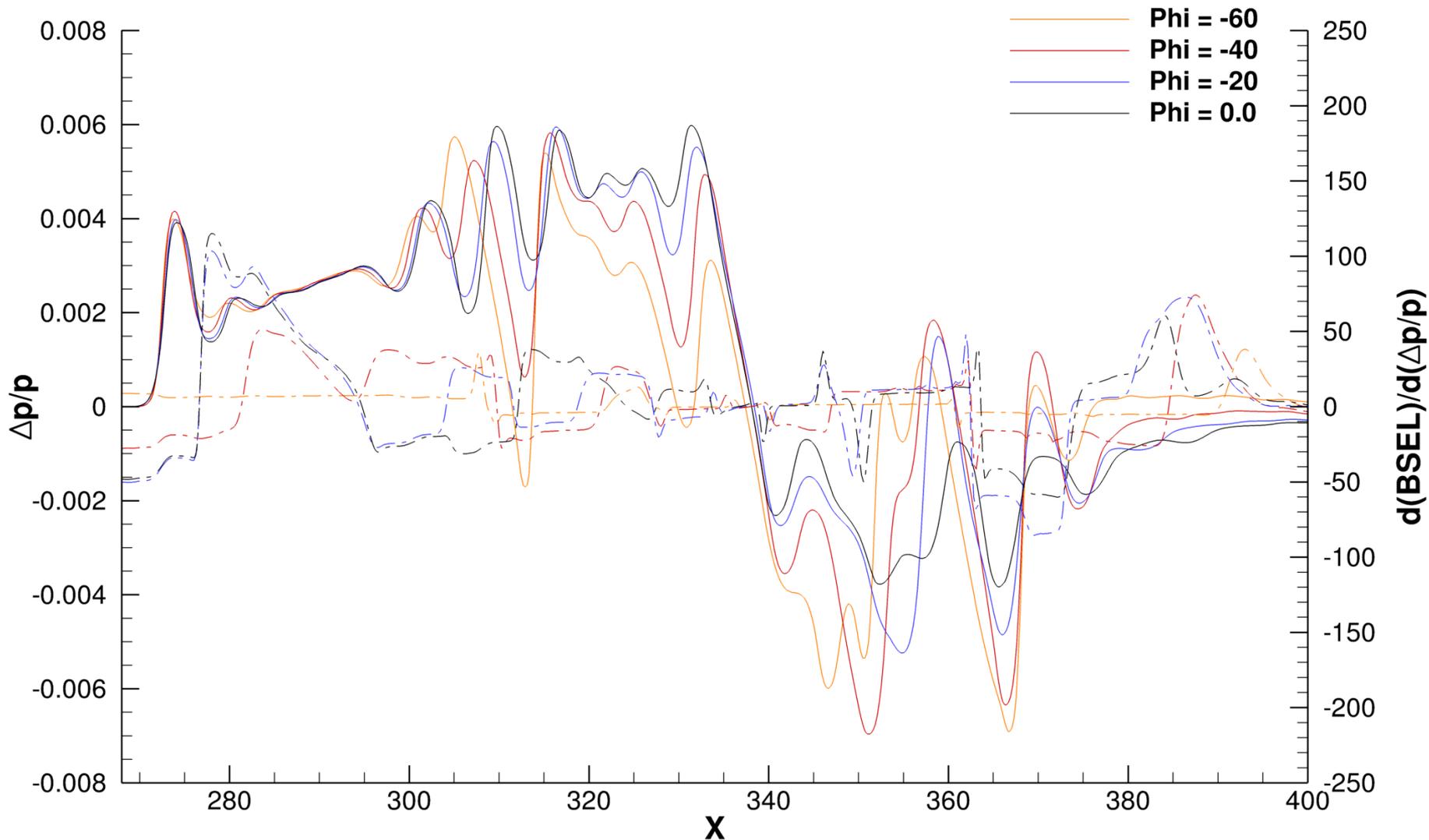
# Highlights: Loudness Build-up



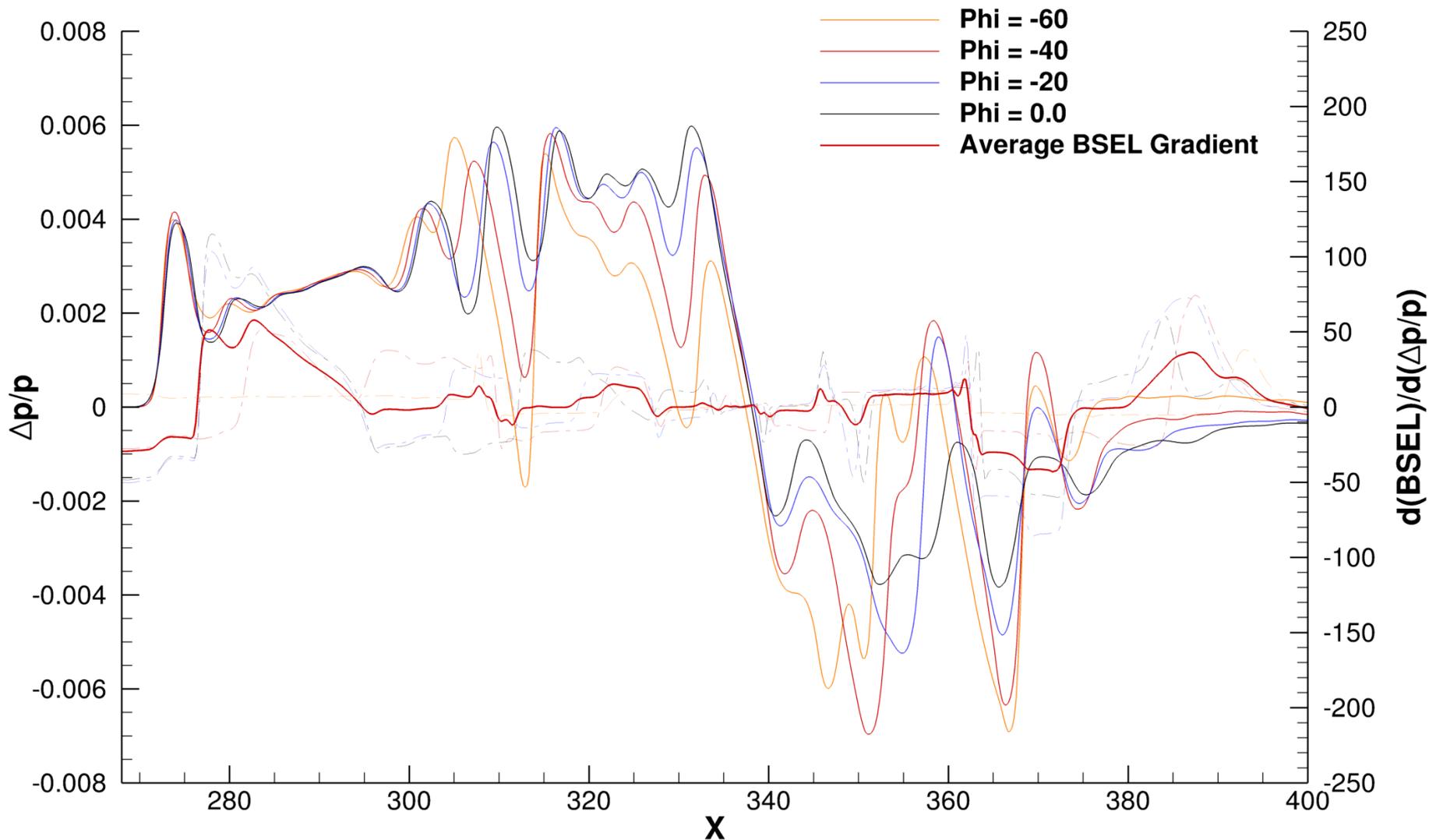
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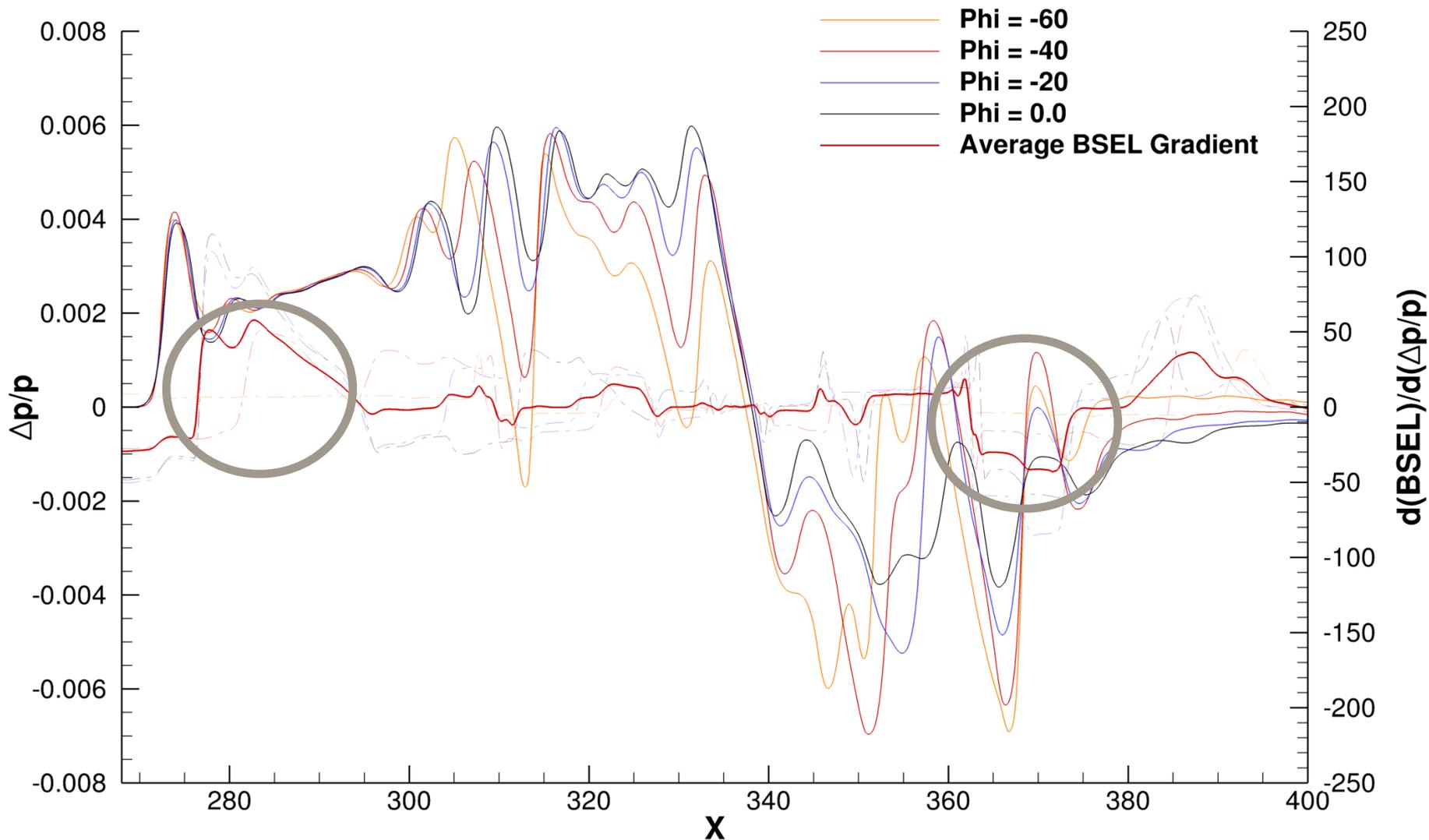
# Highlights: Loudness Gradients



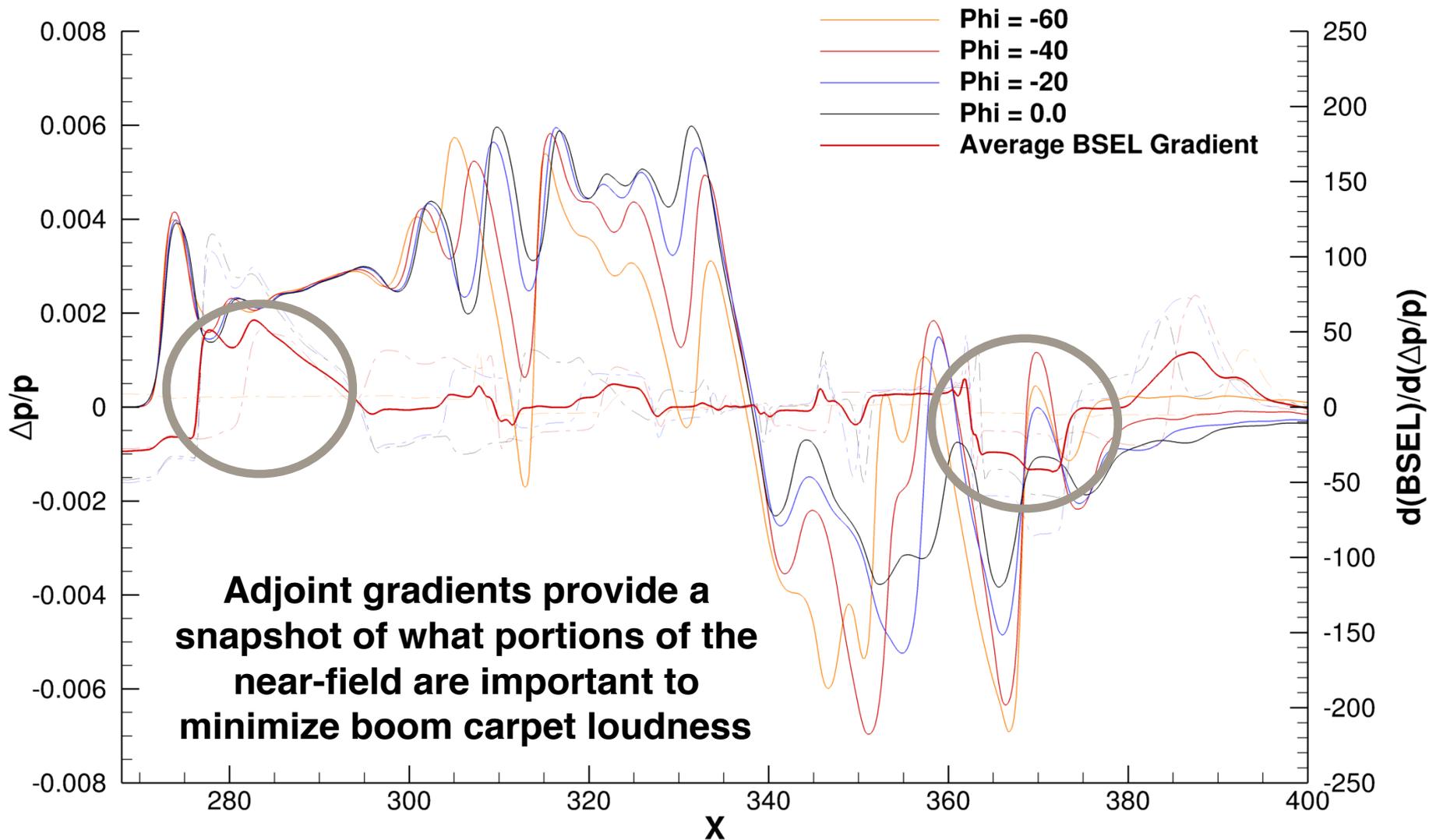
# Highlights: Loudness Gradients



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# Highlights: Loudness Gradients



# Summary

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- Near-field waveforms propagated using sBOOM
- Lateral cut-off azimuths using standard atmospheres are usually quite different from measured/realistic atmospheres
  - Lateral cut-off rays in realistic atmospheres can travel far
  - Could have low grazing angles
- Focus predictions show much higher loudness values than cruise booms (as expected)
- Different implementation of the underlying mechanisms seem to change the underlying characteristics of the ground signatures
  - Poisson vs. Acoustic Potential solutions
  - Wind considerations
  - As loudness levels get lower, there is potential for numerical noise to increase
- Loudness build-up plots can localize the loudness dominating portions of the signatures
- Loudness gradients provide a snapshot to allow optimization of the OML

# Summary

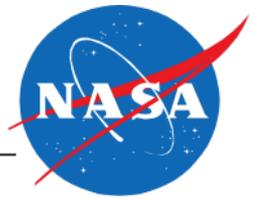
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# Acknowledgments

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- **NASA Commercial Supersonic Technology (CST) Project**
- **Boom prediction workshop organizing committee**

Thank You! – Any Questions?

